

The canonical symplectic structure on a cotangent bundle

Define the map $\pi_Q: T^*Q \rightarrow Q$
 by $\pi_Q(\mu_q) := q \quad \forall \mu_q \in T_q^*Q$,
 and the canonical 1-form Θ_0 on T^*Q
 by $\Theta_0(\mu_q) \cdot v_{\mu_q} := \underbrace{\mu_q}_{\in T_q^*Q} \cdot \underbrace{(d_{\mu_q} \pi_Q \cdot v_{\mu_q})}_{\in T_q Q}$.

Example 1 $Q = \mathbb{R}^n$

$$\pi_{\mathbb{R}^n}(q, p) = q, \quad d_{(q,p)} \pi_{\mathbb{R}^n}(v, w) = (q, v).$$

$$\begin{aligned} \Theta_0(q, p) \cdot (q, p, v, w) &= (q, p) \cdot (q, v) \\ &= \langle p, v \rangle. \end{aligned}$$

Example 2 $Q = G \subseteq GL(n)$.

~~$\pi_G: T^*G \rightarrow G$~~ Define $\tilde{\tau}_{L, \mathbb{R}}: G \times \mathfrak{g}^* \rightarrow T^*G$

$$\text{by } \tilde{\tau}_L(q, \mu) := -g^{-T} \mu$$

$$\text{and } \tilde{\tau}_R(q, \mu) := \mu g^{-T},$$

~~Then~~ if \mathfrak{g}^* is identified with \mathfrak{g}
 using the standard matrix inner
 product.

$$\begin{aligned}\tilde{\tau}_L(g, \mu) \cdot \tau_L(g, \xi) &= \langle g^{-T} \mu, g \xi \rangle \\ &= \langle \mu, \xi \rangle;\end{aligned}$$

similarly, $\tilde{\tau}_R(g, \mu) \cdot \tau_R(g, \xi) = \langle \mu, \xi \rangle$.

$$\pi_G(\tilde{\tau}_L(g, \mu)) = g.$$

We'll compute $\tilde{\Theta}_0 := \tilde{\tau}_L^* \Theta_0$, a 1-form on $T(G \times \mathfrak{g}^*) \simeq TG \times \mathfrak{g}^* \times \mathfrak{g}^*$.

$$\begin{aligned}d_{(g, \mu)}(\pi_G \circ \tilde{\tau}_L) \cdot (\tau_L(g, \xi), \mu, \nu) \\ = \tau_L(g, \xi).\end{aligned}$$

$$\begin{aligned}\text{Hence } \tilde{\Theta}_0(g, \mu) \cdot (\tau_L(g, \xi), \mu, \nu) \\ = \tilde{\tau}_L(g, \mu) \cdot d_{(g, \mu)}(\pi_G \circ \tilde{\tau}_L) \cdot (\tau_L(g, \xi), \mu, \nu) \\ = \tilde{\tau}_L(g, \mu) \cdot \tau_L(g, \xi) \\ = \langle \mu, \xi \rangle.\end{aligned}$$

Given a 1-form β on Q , $\beta^* \Theta_0 = \beta$.

$$\begin{aligned}\text{Pf: } (\beta^* \Theta_0)(q) \cdot v_q &= \Theta_0(\beta(q)) \cdot (d_q \beta \cdot v_q) \\ &= \beta(q) \cdot d_{\beta(q)} \pi_Q (d_q \beta \cdot v_q) \\ &= \beta(q) \cdot (d_q (\pi_Q \circ \beta) \cdot v_q) \\ &= \beta(q) \cdot v_q\end{aligned}$$

3

since $\Pi_q \circ \beta = \text{id}$ $\begin{array}{ccc} & T^*Q & \\ \beta \uparrow & & \searrow \Pi_q \\ & Q & \end{array}$.

Introduce construction $\text{vert}_{\mu_q}: T_q^*Q \rightarrow T(T^*Q)$,

$$\text{vert}_{\mu_q}(v_q) := \frac{d}{d\varepsilon} \mu_q + \varepsilon v_q \Big|_{\varepsilon=0},$$

vertical lift of v_q .

$$\begin{aligned} d_{\mu_q} \Pi_q \cdot \text{vert}_{\mu_q}(v_q) &= \frac{d}{d\varepsilon} \Pi_q(\mu_q + \varepsilon v_q) \Big|_{\varepsilon=0} \\ &= \frac{d}{d\varepsilon} q \Big|_{\varepsilon=0} \\ &= 0. \end{aligned}$$

Hence $\Theta_0(\mu_q) \cdot \text{vert}_{\mu_q}(v_q) = 0$

for any $\mu_q, v_q \in T_q^*Q, q \in Q$.

vert_{μ_q} is 1-1, so $\text{vert}_{\mu_q}(T_q^*Q)$ is isomorphic to T_q^*Q .

If $\mu_q = \beta(q)$ for some 1-form β on Q , then given $w_{\mu_q} \in T_{\mu_q}(T^*Q)$, let $v_q := d_{\mu_q} \Pi_q \cdot w_{\mu_q} \in T_qQ$.

Claim: $\exists v_q \in T_q^*Q$ such that $w_{\mu_q} = d_q \beta \cdot v_q + \text{vert}_{\mu_q}(v_q)$.

Sketch of proof:

$$d_{\mu_g} \Pi_Q \cdot (\omega_{\mu_g} - d_g \beta \cdot v_g) = v_g - d_g (\Pi_Q \circ \beta) \cdot v_g = 0.$$

Hence it suffices to show that

$$\text{vert}_{\mu_g}(T_g^* Q) = \ker(d_{\mu_g} \Pi_Q).$$

We know $\text{vert}_{\mu_g}(T_g^* Q) \subseteq \ker(d_{\mu_g} \Pi_Q)$,

and $\dim(\text{vert}_{\mu_g}(T_g^* Q)) = \dim Q$,

since it's isomorphic to $T_g^* Q$.

$$\text{Since } \text{range}(d_{\mu_g} \Pi_Q) = T_g Q,$$

$$\text{rank}(d_{\mu_g} \Pi_Q) = \dim Q, \text{ so}$$

$$\begin{aligned} \text{nullity}(d_{\mu_g} \Pi_Q) &= \dim(T_g^* Q) - \text{rank}(d_{\mu_g} \Pi_Q) \\ &= 2 \dim Q - \dim Q \\ &= \dim(\text{vert}_{\mu_g}(T_g^* Q)). \end{aligned}$$

Given a relevant / natural choice of β , we can regard $d_g \beta \cdot v_g$ as a plausible choice of a variation of configuration with "fixed" momentum - not intrinsic, though.

$\text{vert}_{\mu_g}(v_g)$ is a entirely natural variation of momentum with fixed configuration.

Canonical symplectic structure on T^*Q

The canonical symplectic structure on T^*Q is $\omega := -d\Theta$, i.e. minus the exterior derivative of the canonical 1-form. (Caution: This sign convention is not universal.)

Mini-review of exterior differentiation:

d is the unique map taking k -forms to $(k+1)$ -forms that satisfies

i) $d^2 f = df$, the conventional differential, if f is a 0-form, i.e. scalar function.

ii) d is an anti-derivation:

$$d(\lambda B) = \lambda dB \quad \forall \lambda \in \mathbb{R}, \text{ and } \forall k\text{-forms } B$$

$$d(\alpha \wedge B) = (d\alpha) \wedge B + (-1)^k \alpha \wedge (dB) \quad \forall k\text{-forms } \alpha \text{ and } l\text{-forms } B$$

iii) $d(dB) \equiv 0 \quad \forall$ forms B

iv) d is natural with respect to restrictions: if B is defined on M and U is a subset of M , then $(dB)|_U = d(B|_U)$.

61

Important property: d commutes with pullback: $\varphi^*(d\beta) = d(\varphi^*\beta)$.

Very important property: "Cartan's magic formula": Given a vector field X and form β ,

$$L_X \beta = L_X d\beta + d(L_X \beta)$$

Back to canonical symplectic structure:

Strategy for computing ω : Given $\mu_q \in T^*Q$ and $v_{\mu_q}, w_{\mu_q} \in T_{\mu_q} T^*Q$, choose 'convenient' vector fields X and Y such that $X(\mu_q) = v_{\mu_q}$, $Y(\mu_q) = w_{\mu_q}$. Then

$$\begin{aligned} \omega(\mu_q)(v_{\mu_q}, w_{\mu_q}) &= \omega(\mu_q)(X(\mu_q), Y(\mu_q)) \\ &= (L_Y L_X \omega)(\mu_q) \\ &= -(L_Y L_X d\theta_0)(\mu_q) \\ &= -L_Y (L_X \theta_0 - d(L_X \theta_0))(\mu_q). \end{aligned}$$

Often convenient to further use identity

$$L_X (L_Y \beta) = L_{L_X Y} \beta + L_Y (L_X \beta),$$

getting

$$\omega(\mu_q)(V_{\mu_q}, W_{\mu_q}) = \langle L_{\nu}(\iota_x \Theta_0) - L_x(\iota_{\nu} \Theta_0) + L_{x\nu} \Theta_0 \rangle(\mu_q)$$

For example, if $\mu_q = \beta(q)$ for some 1-form β on Q , then $\exists s_q, u_q \in T_q Q$ and $v_q, t_q \in T_q^* Q$ such that

$$V_{\mu_q} = d_q \beta \cdot s_q + \text{vert}_{\mu_q}(v_q)$$

$$W_{\mu_q} = d_q \beta \cdot u_q + \text{vert}_{\mu_q}(t_q)$$

$$\omega(\mu_q)(V_{\mu_q}, W_{\mu_q}) = (\beta^*(-d\Theta_0))(\mu_q)(s_q, u_q) + \omega(\mu_q)(\text{vert}_{\mu_q}(v_q), d_q \beta \cdot u_q) \text{ etc.}$$

First term satisfies

$$\begin{aligned} & (\beta^*(-d\Theta_0))(\mu_q)(s_q, u_q) \\ &= -d(\beta^* \Theta_0)(\mu_q)(s_q, u_q) \\ &= -d\beta(q)(s_q, u_q) \end{aligned}$$

Simplifications for terms of form $\omega(\mu_q)(\text{vert}_{\mu_q}(v_q), \cdot)$?

Choose 1-form γ such that $v_q = \gamma(q)$ and define the vector field X on T^*Q

98

by $X(\mu_g) := \text{vert}_{\mu_g}(\gamma(g))$.

Flow map F_ε of X is $F_\varepsilon(\mu_g) = \mu_g + \varepsilon \gamma(g)$;
note that flow never leaves the fiber —
hence $\pi_q \circ F_\varepsilon = \pi_q$.

$$\begin{aligned} (L_X \Theta_0)(\mu_g)(z_{\mu_g}) &= \frac{d}{d\varepsilon} (F_\varepsilon^* \Theta_0)(\mu_g)(z_{\mu_g}) \Big|_{\varepsilon=0} \\ &= \frac{d}{d\varepsilon} \cdot F_\varepsilon(\mu_g) \cdot (d_{\mu_g}(\pi_q \circ F_\varepsilon) \cdot z_{\mu_g}) \Big|_{\varepsilon=0} \\ &= \frac{d}{d\varepsilon} (\mu_g + \varepsilon \gamma(g)) \cdot (d_{\mu_g} \pi_q \cdot z_{\mu_g}) \Big|_{\varepsilon=0} \\ &= \gamma(g) \cdot (d_{\mu_g} \pi_q \cdot z_{\mu_g}). \end{aligned}$$

Since $L_X \Theta_0 = 0$, it follows that

$$\begin{aligned} \omega(\mu_g)(\text{vert}_{\mu_g}(\gamma(g)), z_{\mu_g}) \\ &= - (L_X \Theta_0)(\mu_g)(z_{\mu_g}) \\ &= - \gamma(g) \cdot (d_{\mu_g} \pi_q \cdot z_{\mu_g}) \\ &= - \gamma(g) \cdot (d_{\mu_g} \pi_q \cdot z_{\mu_g}). \end{aligned}$$

Substituting into the expansion of $\omega(\mu_g)(U_{\mu_g}, W_{\mu_g})$,
we find

$$\begin{aligned} \omega(\mu_g)(U_{\mu_g}, W_{\mu_g}) &= - dB(g)(s_g, u_g) \\ &\quad - \gamma(g) \cdot (d_{\mu_g} \pi_q \cdot d_g B \cdot u_g) \\ &\quad + \gamma(g) \cdot (d_{\mu_g} \pi_q \cdot d_g B \cdot s_g) + 0 \end{aligned}$$

$$= T_q \cdot s_q - \nabla_q \cdot u_q - d B(q)(s_q, u_q)$$

Exercise: $Q = \mathbb{R}^n$

Let $p_q = (q, p)$, set $B(q) = (q, p)$, so

$$B(q) \cdot (q, v) = \langle p, v \rangle$$

Show the above formula reduces to

$$\begin{aligned} \omega(q, p) \left((q, p, v_1, w_1), (q, p, v_2, w_2) \right) \\ = \langle w_2, v_1 \rangle - \langle w_1, v_2 \rangle \end{aligned}$$