

Dynamics of Gels

part 4

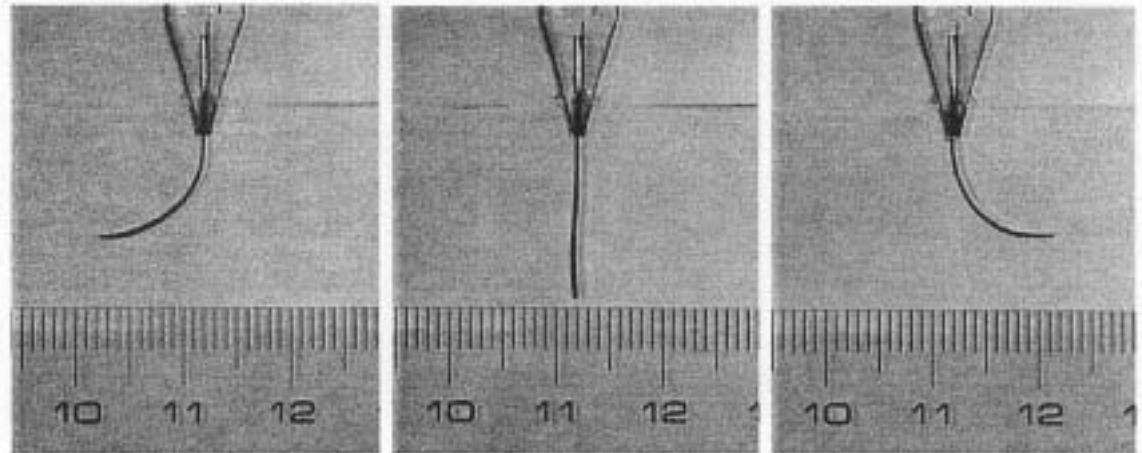
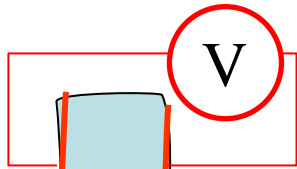
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Outline

1. What are gels: problems to be discussed
2. Basic equations for gel dynamics: linear model
3. Applications:
 - Swelling of constrained gel
 - Swelling of cylindrical gel
4. Basic equations for gel dynamics: non-linear model
 - Theory of elasticity for large deformation
 - Volume transition
5. Electro-kinetic effect

Electro Responsive Gel

Electric field causes deformation of ionic gels.

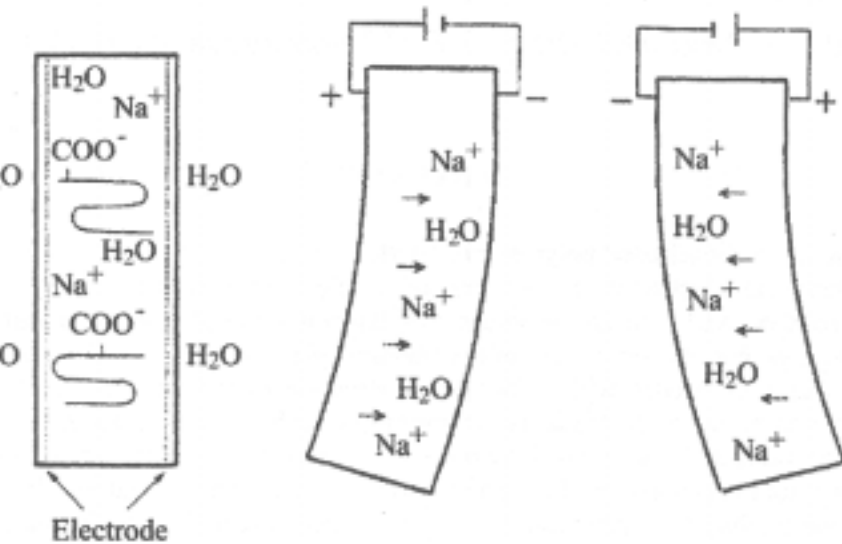


Nafion
Oguro et al

EAMEX

EAMEX

Mechanism



Asaka et al (1995, 2000)

Water is carried by mobile ions.

de Gennes et al (2000)

Electro Mechanical Coupling

Electric current

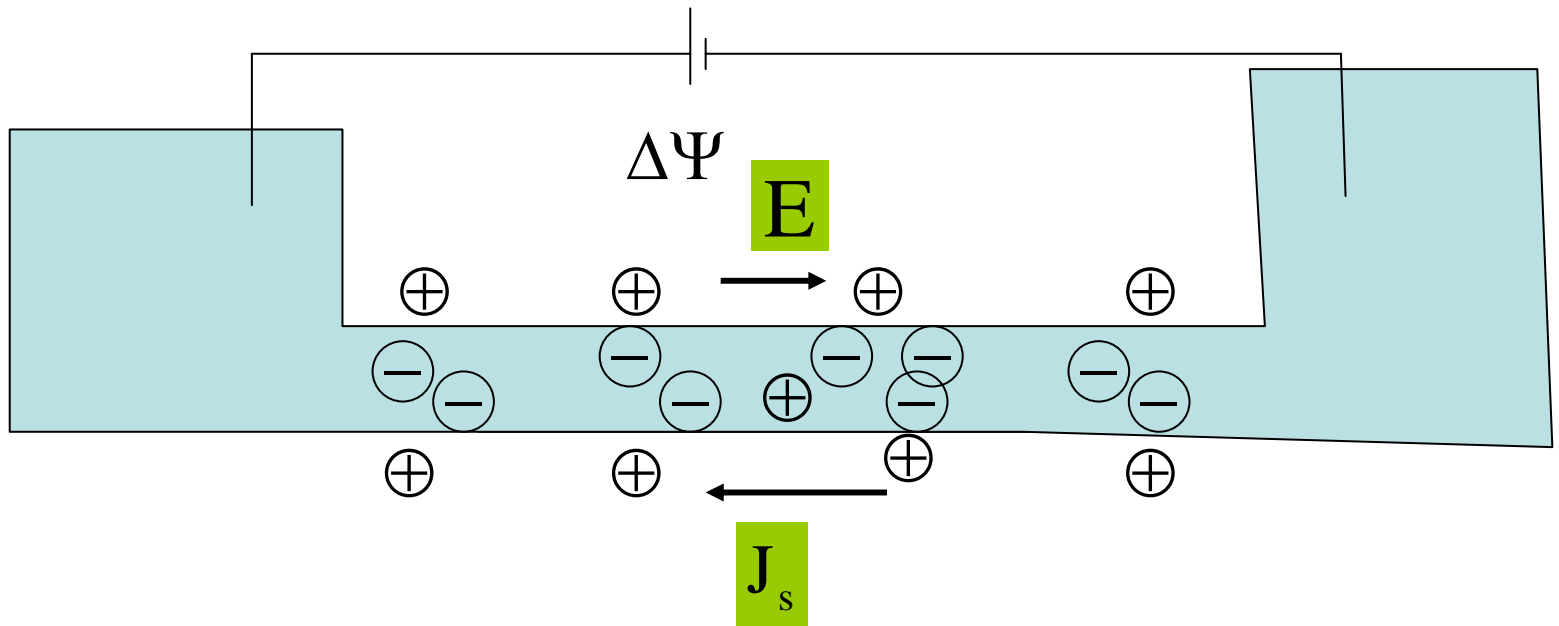
$$\mathbf{J} = -\sigma \nabla \psi - \lambda \nabla p$$

Water flux

$$\mathbf{J}_s = -\kappa \nabla p - \lambda \nabla \psi$$

Electro-Osmosis

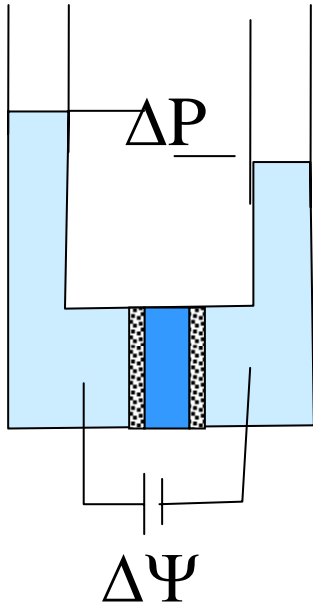
$$\mathbf{J}_s = -\kappa \nabla p - \lambda \nabla \psi$$



Electro-mechanical coupling

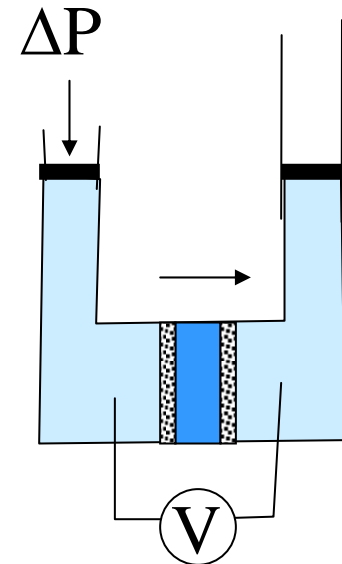
$$J = -\sigma \nabla \psi - \lambda \nabla p$$

$$J_s = -\kappa \nabla p - \lambda \nabla \psi$$



Electro osmosis

$$\Delta P = -\frac{\lambda}{\kappa} \Delta \Psi$$



Streaming potential

$$\Delta \Psi = -\frac{\lambda}{\sigma} \Delta P$$

Basic Equations for Ionic Gels

$$\nabla \cdot (-p\mathbf{I}) = 0$$

mechanical balance

$$\mathbf{J}_s = -\kappa \nabla \cdot \mathbf{p} - \lambda \nabla \psi$$

water flow

$$\nabla \cdot [\phi \mathbf{v}_p + (1 - \phi) \mathbf{v}_s] = 0$$

incompressible

$$\mathbf{J} = -\sigma \nabla \cdot \psi - \lambda \nabla p$$

electric current

$$\nabla \cdot \mathbf{J} = 0$$

charge neutrality

“Derivation” of Basic Equations

$$\zeta_i (\mathbf{v}_i - \mathbf{v}_s) = -q_i \nabla \psi \quad \text{ions}$$

$$\zeta_p c_p (\dot{\mathbf{u}} - \mathbf{v}_s) = \nabla \cdot \boldsymbol{\sigma} - \phi \nabla p - c_p q_p \nabla \psi \quad \text{polymer}$$

$$\zeta_p c_p (\mathbf{v}_s - \dot{\mathbf{u}}) + \zeta_i c_i (\mathbf{v}_s - \mathbf{v}_i) = (1 - \phi) \nabla p \quad \text{water}$$

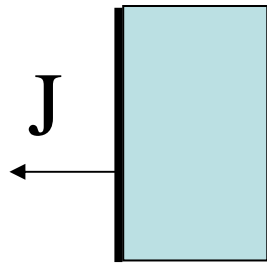
$$\mathbf{J}_s = (1 - \phi) (\mathbf{v}_s - \dot{\mathbf{u}}) \quad \text{water flux}$$

$$\mathbf{J} = \sum_i c_i q_i (\mathbf{v}_i - \dot{\mathbf{u}}) \quad \text{electric current}$$

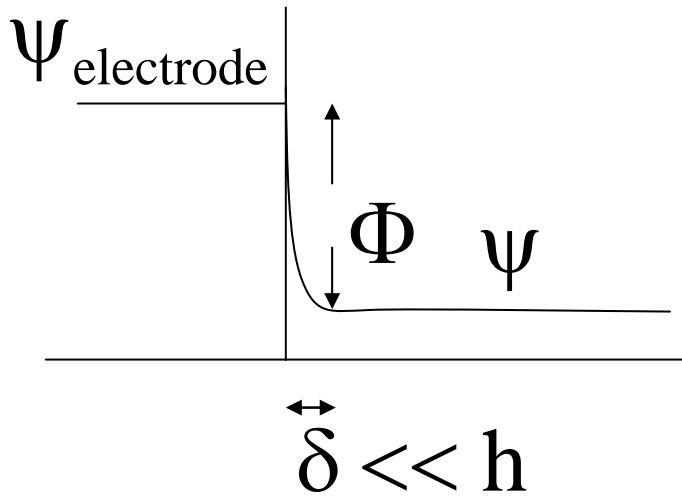
$$\kappa = \frac{(1 - \phi)^2}{c_p \zeta_p} \quad \boldsymbol{\sigma} = \frac{c_p q_p^2}{\zeta_p} + \sum_i \frac{c_i q_i^2}{\zeta_i} \quad \lambda = \frac{q_p (1 - \phi)}{\zeta_p}$$

Boundary Condition 1

Condition for electric field and current



$$\mathbf{J} \cdot \mathbf{n} = \begin{cases} \dot{Q} & \Phi < \Phi_c \\ \mathbf{J}_{\text{electrode}}(\Phi) & \Phi > \Phi_c \end{cases}$$

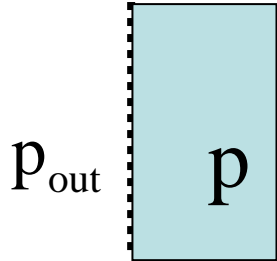


$$\psi = \psi_{\text{electrode}} - \Phi(Q)$$

Boundary Condition 2

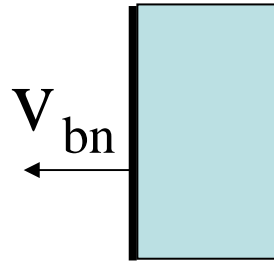
Condition for solvent

permeable wall



$$p = p_{out}$$

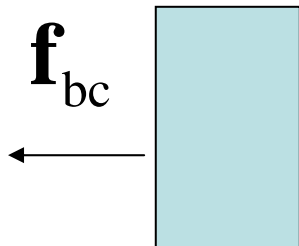
Impermeable wall



$$V_{sn} = V_{bn}$$

Condition for polymer

deformable boundary



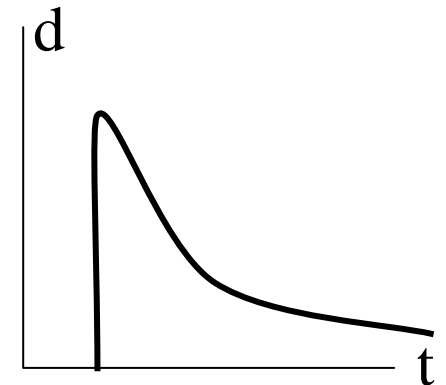
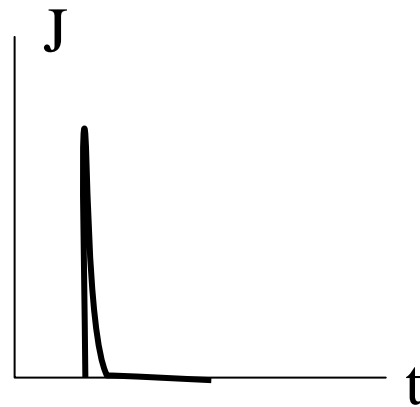
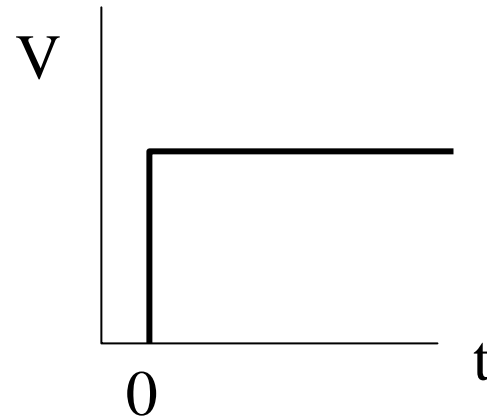
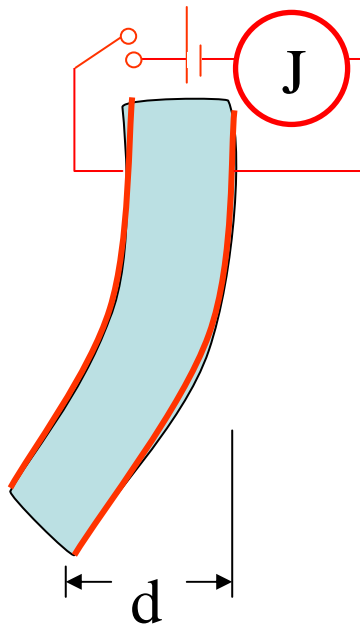
$$(-p\mathbf{I}) \cdot \mathbf{n} = \mathbf{f}_{bc}$$

gel fixed to the boundary

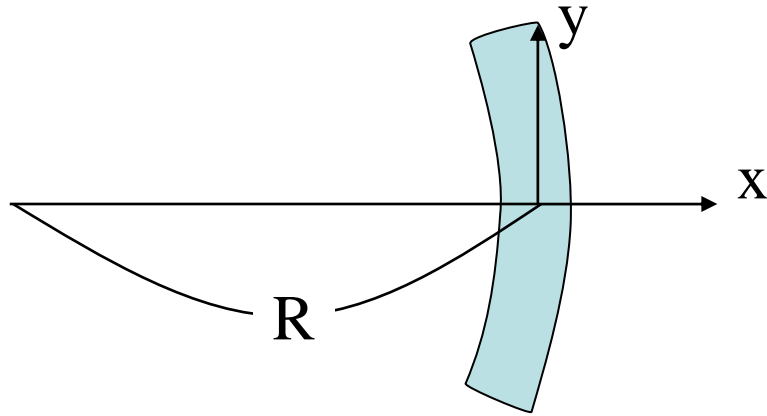


$$\mathbf{u}_p = \mathbf{u}_b$$

Analysis of the Step Voltage Case



Mechanical Balance



$$u_x(x, t)$$

$$u_y = \frac{xy}{R}, u_z = \frac{xz}{R}$$

$$\sigma_{xx} = \left(K + \frac{4}{3}G\right)\beta - \frac{4G}{R}x$$

$$\sigma_{yy} = \left(K - \frac{2}{3}G\right)\beta + \frac{2G}{R}x$$

$$P = \sigma_{xx}$$

$$\int_{-h}^h dx (\sigma_{yy} - P)x = 0$$

$\sigma_{xx}, \sigma_{yy}, \sigma_{zz}$ are written by

$\beta(x, t) = \nabla \cdot \mathbf{u}$ and $R(t)$.

Force balance in x direction

Torque balance

$$\frac{1}{R(t)} = \frac{1}{h^3} \int_0^h dx \beta(x, t)x$$

Initial Condition

Assume that the charging up of the electric double layer is very fast.

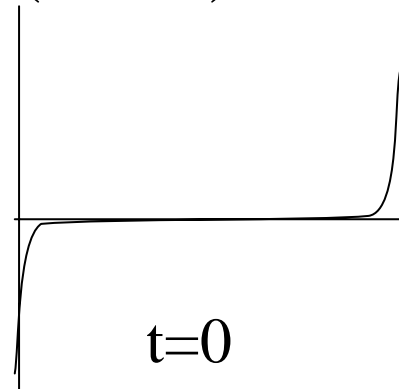
$$\text{For } t < \tau_s \quad \mathbf{J} = -\sigma \nabla \cdot \psi$$

$$\nabla p = 0 \quad \mathbf{J}_s = -\lambda \nabla \psi$$

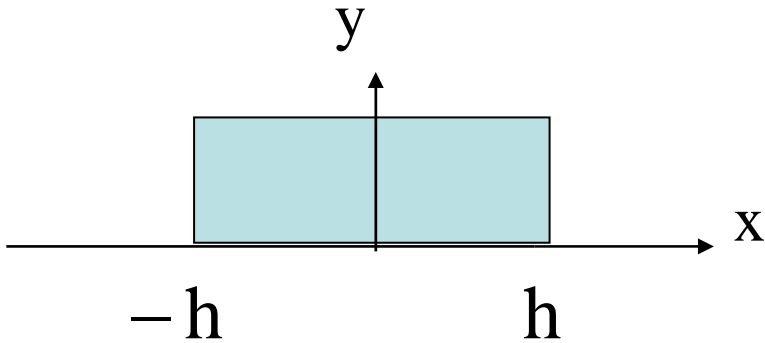
$$\text{Total amount of water transferred} \quad w = \frac{\lambda}{\sigma} Q$$

$$\beta(x, t = 0) = -w\delta(x + h) + w\delta(x - h)$$

$$\frac{1}{R(0)} = \frac{2\lambda}{h^2 \sigma} Q$$



Relaxation



$$\mathbf{J} = -\sigma \nabla \psi - \lambda \nabla p$$

$$\mathbf{J}_s = -\kappa \nabla p - \lambda \nabla \psi$$

$$\mathbf{J} = 0 \quad \swarrow \quad \searrow$$

$$\mathbf{J}_s = -\left(\kappa - \frac{\lambda^2}{\sigma} \right) \frac{\partial p}{\partial x}$$

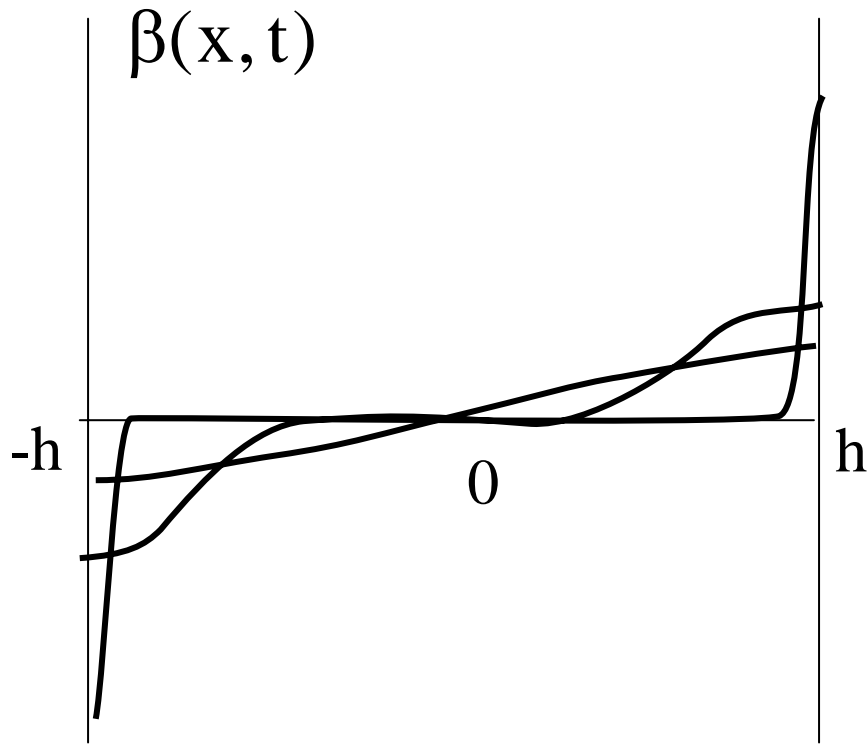
$$\frac{\partial \beta}{\partial t} = D' \frac{\partial^2 \beta}{\partial x^2}$$

$$D' = \kappa \left(1 - \frac{\lambda^2}{\kappa \sigma} \right) \left(K + \frac{4}{3} G \right)$$

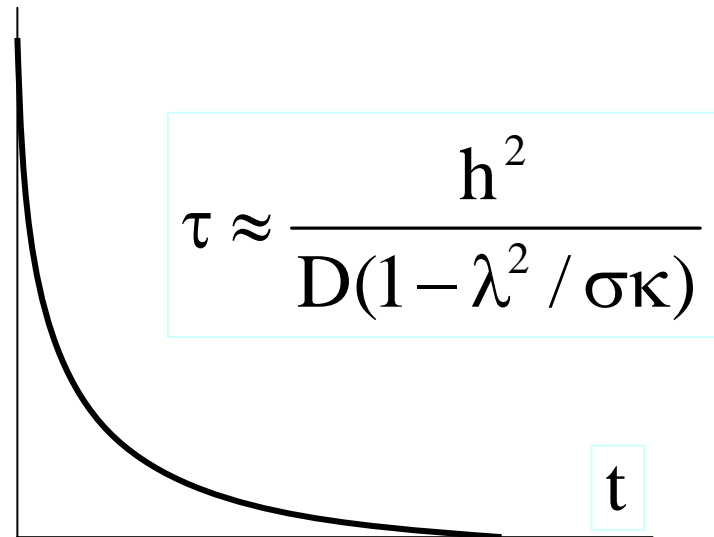
$$\frac{\partial \beta}{\partial x} = \frac{4G}{K + (4/3)G} \frac{1}{R}$$

$$\frac{1}{R(t)} = \frac{1}{h^3} \int_0^h dx \beta(x, t) x$$

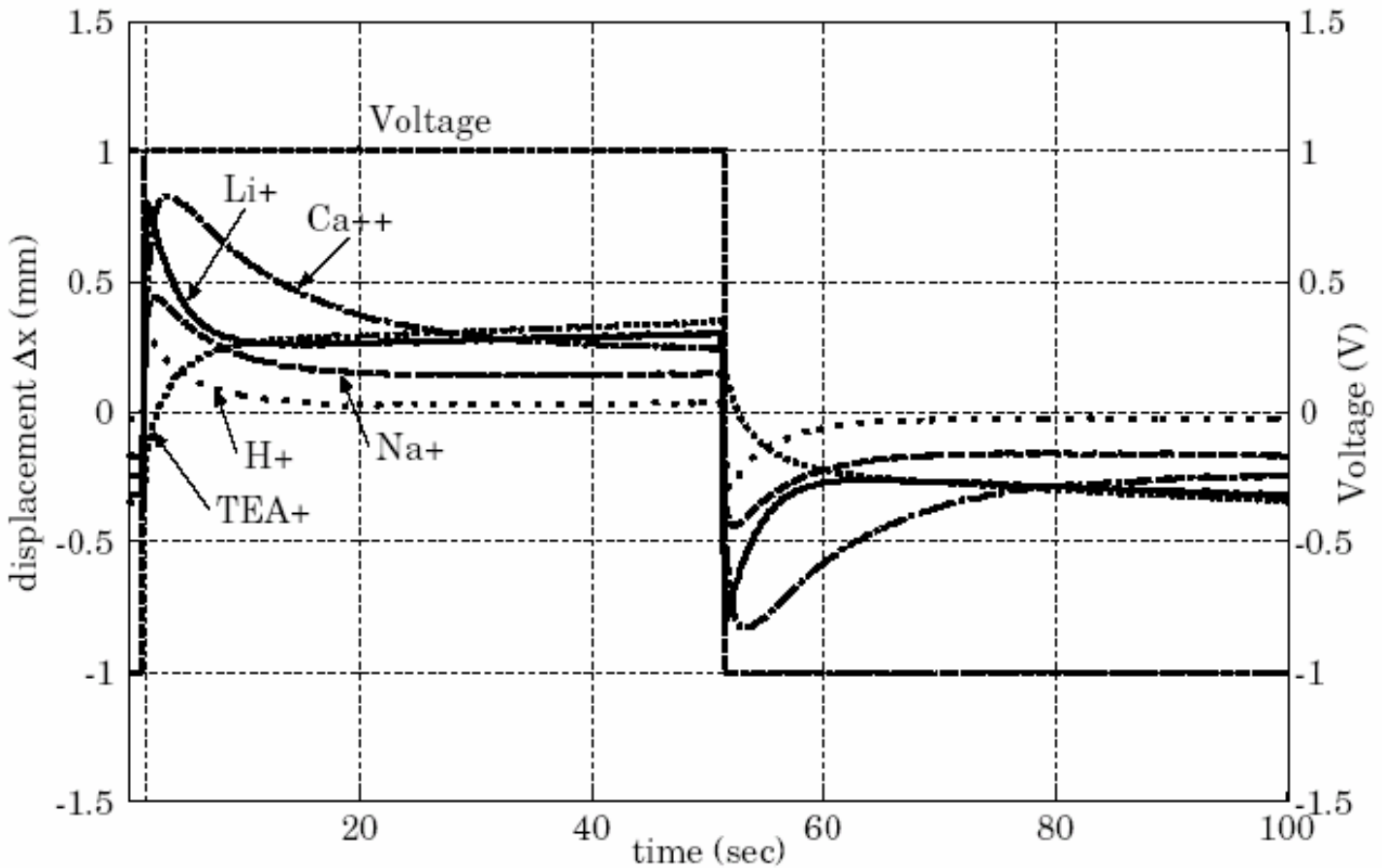
Time Evolution



Bending

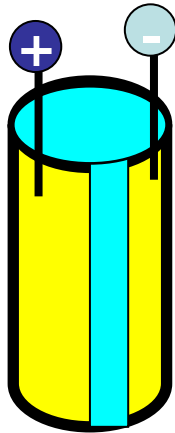


Experimental results

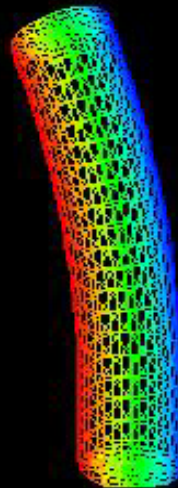
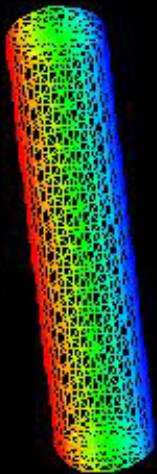


Gel does not become straight as $t \rightarrow \infty$

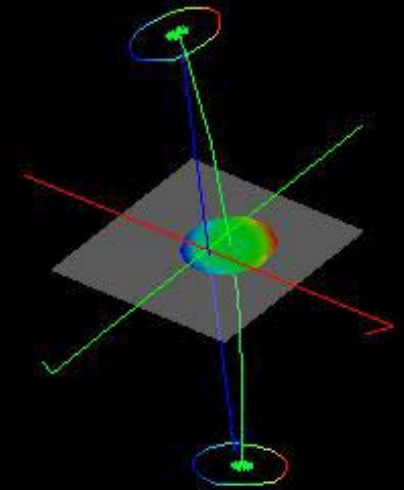
Deformation of Cylindrical Gel



Taniguchi and Yamaue



$=0.3$



Ion distribution

Conclusion

- The dynamics of ionic gel involves electro-stress-diffusion coupling
 - solvent diffusion
 - deformation of gel
 - electric field
- A complete set of equations for the phenomena has been established, but it has not been studied extensively.
- Application:
 - artificial muscle, biomechanics, fuel cell