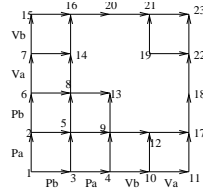
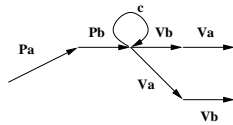


## Some properties of interest

All processes are (discrete in general) dynamical systems = directed graphs of actions  $\rightarrow$  some kind of fibred product.

$PbPaVbVa \mid PaPbVaVb$ :

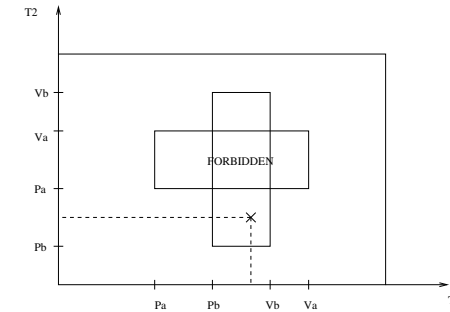


- 3 -

## Geometry

First idea: "Progress graphs" E.W.Dijkstra'68 (later V.Pratt'91)

$T1=Pa.Pb.Vb.Va$  in parallel with  $T2=Pb.Pa.Va.Vb$



"Continuous image":  $x_i$  = local time; dashed rectangles=**forbidden!**

- 4 -

## Directed topology and Concurrency: an introduction

Eric Goubault

CEA/Saclay

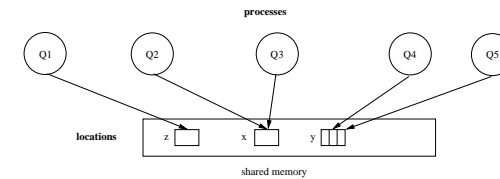
Eric.Goubault@cea.fr

<http://www.di.ens.fr/~goubault>

- 1 -

## Concurrency and Geometry?

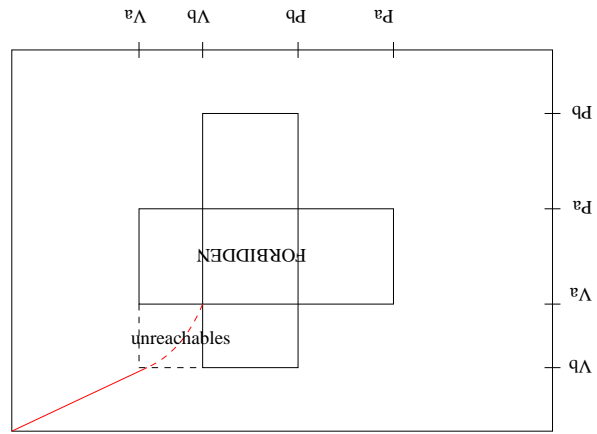
(here, shared memory style)



$\neq$  sequential; problem of coordination (need for locks  $P, V$ )  
 Is the coordination too constrained?  $\rightarrow$  deadlocks  
 Do we have "bad" states?  $\rightarrow$  reachability  
 Are the sequences of accesses "right"?  $\rightarrow$  paths...

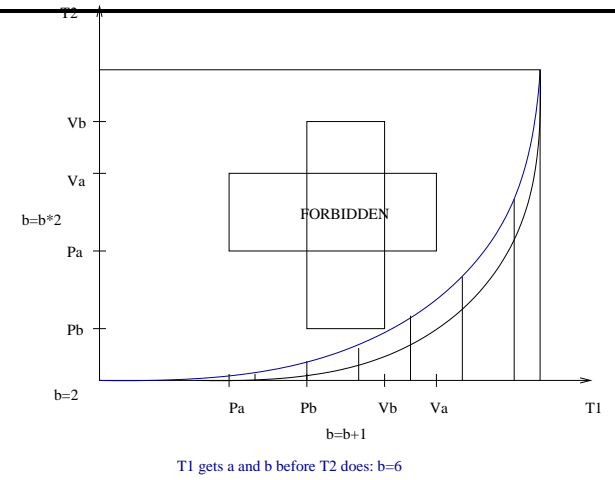
- 2 -

## And dually...



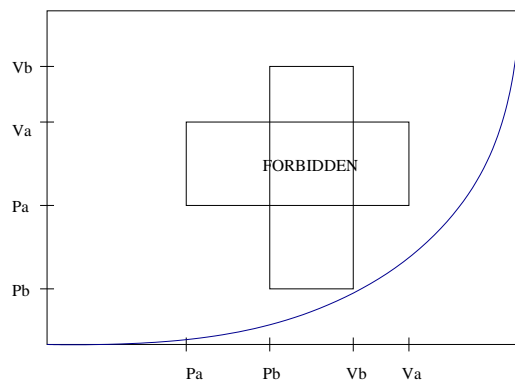
- 7 -

## Deformation of execution paths



- 8 -

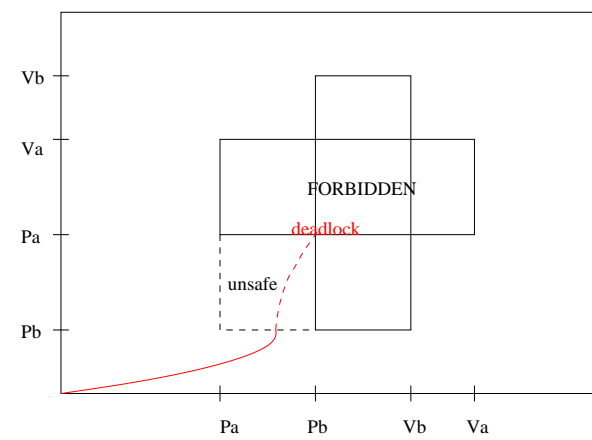
## Execution paths



Traces = paths increasing in each coordinate = "di-paths"

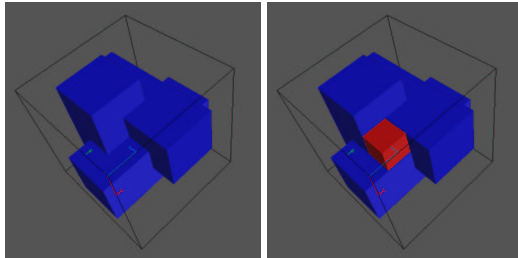
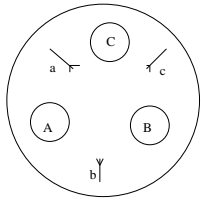
- 5 -

## First remark



- 6 -

## In higher-dimension

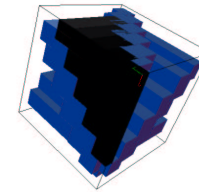


$A = Pa . Pb . Va . Vb$   
 $B = Pb . Pc . Vb . Vc$   
 $C = Pc . Pa . Vc . Va$

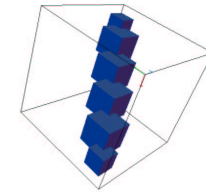
- 11 -

## Also: effect of the level of sharing

$A = Pa . Pb . Va . Pc . Vb . Pd . Vc . Pe . Vd . Pf . Ve . Vf$   
 $B = Pf . Pe . Vf . Pd . Ve . Pc . Vd . Pb . Vc . Pa . Vb . Va$   
 $C = Pf . Pe . Vf . Pd . Ve . Pc . Vd . Pb . Vc . Pa . Vb . Va$



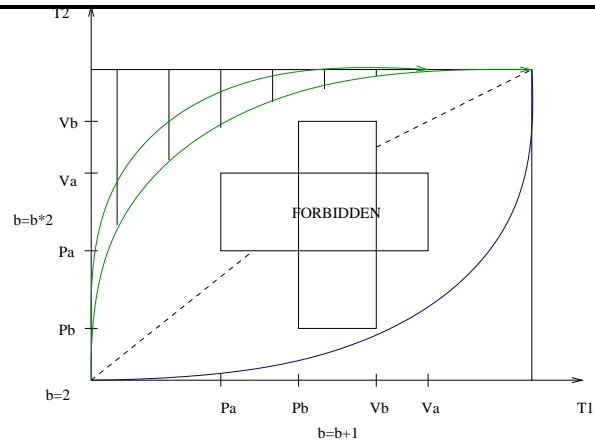
$a, \dots$  binary sem.



$a, \dots$  counting sem.

- 12 -

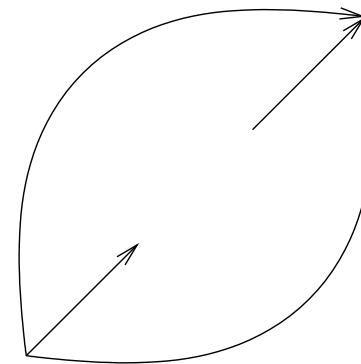
## Non-deformable paths



T2 gets a and b before T1 does:  $b=5!$

- 9 -

## Ideally...*(not quite true though)*



We will get back to this later...

- 10 -

## Po-spaces

For “Progress Graphs”, one only needs (MFPS’98):

A topological space with a (global) closed partial order

- Morphisms are **increasing and continuous** maps
- (Finite) Traces on  $(X, <)$  are dimaps from  $\vec{I} = ([0, 1], \leq)$  to  $(X, <)$  (dipaths).
- Dihomotopies between dipaths  $f$  and  $g$  with **fixed extremities**  $\alpha$  and  $\beta$  are dimaps  $H : \vec{I} \times I \rightarrow X$  such that for all  $x \in \vec{I}, t \in I$ ,

$$H(x, 0) = f(x), H(x, 1) = g(x), H(0, t) = \alpha, H(1, t) = \beta$$

Another preferred definition - by M. Grandis, where  $H : \vec{I} \times \vec{I} \rightarrow X$  (some equivalence when  $X$  is a finite precubical set - see Lisbeth’s talk).

## Loops?

$$A = PdPa ( PbVaVdPcVbPaPdVcPbVaPcVbPaVcPbVaPcVbPaVc ) * VaPeVdVe$$

$$B = PePa ( PbVaPcVbPaVcPbVaPcVbPaVc ) * VaPdVeVd$$



## Correspondences (almost...)

Model [discrete]	combinatorial complex
Model [continuous]	topological space
Relation discrete/continuous	geometric realisation
Parallel composition	product
Action refinement	subdivision
Compositionality	Seifert/van Kampen
Deadlocks/reachability	connected components
<a href="#">Scheduling properties</a>	fundamental group
Observational equivalence	homotopy equivalence (weak/strong)
Computable properties	topological invariants (homology etc.)

## Models

- Po-spaces, local po-spaces, (pre-)cubical sets (see MFPS’98, with L. Fajstrup and M. Raussen)
- globular CW-complexes: with P. Gaucher, “Topological Deformation of Higher-Dimensional Automata”, *arXiv:math.AT/0107060*, HHA 2003
- $\Omega$ -categories, Category “Flow” (Philippe Gaucher)
- $d$ -spaces (Marco Grandis)
- Higher-Dimensional Transition Systems (Vladimiro Sassone and Gian Luca Cattani, LICS’96)
- ECHIDNA (Richard Buckland and Michael Johnson, AMAST’96)
- etc.

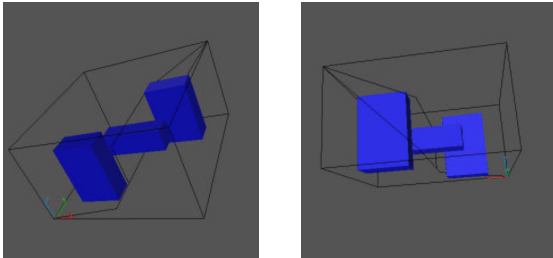
## Second subtlety...

#sem c 2

A=Pa . Pc . Va . Pb . Vc . Vb

B=Pa . Va . Pc . Vc . Pb . Vb

C=Pc . Vc



Directed homotopy is not classical homotopy plus fixed extremities:

- 19 -

## A typical object of study

Use of **fundamental category** (and functor):

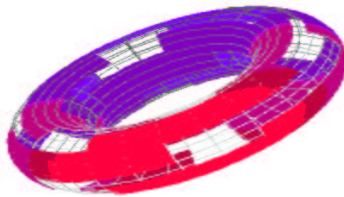
$\vec{\pi}_1(X)$ :

- its objects are the points of  $X$ ,
- its morphisms are dihomotopy classes of dipaths: a morphism from  $x$  to  $y$  is a dihomotopy class  $[f]$  of a dipath  $f$  going from  $x$  to  $y$ .

Generalizes the fundamental group  $\pi_1(X)$  of a topological space  $X$  (a single object=base point; morphisms=homotopy classes of loops).

- 20 -

## Gives...

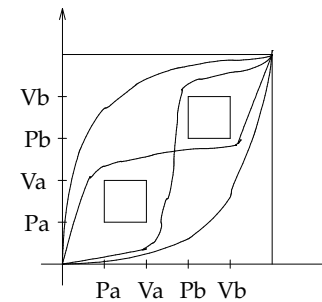


→ local po-space (MFPS'98); manifold like definition, locally a po-space. Extensions of algorithms (see L. Fajstrup, M. Raussen, S. Sokolowski).

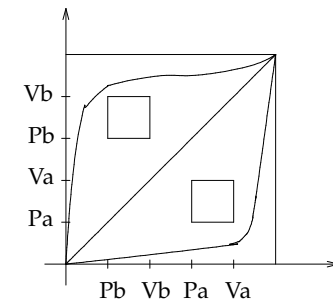
- 17 -

## First subtlety

$PaVaPbVb \mid PaVaPbVb$ :



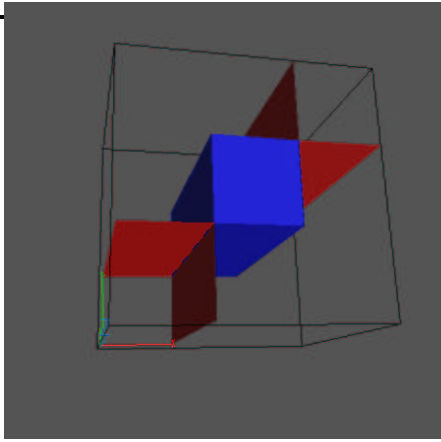
$PbVbPaVa \mid PaVaPbVb$ :



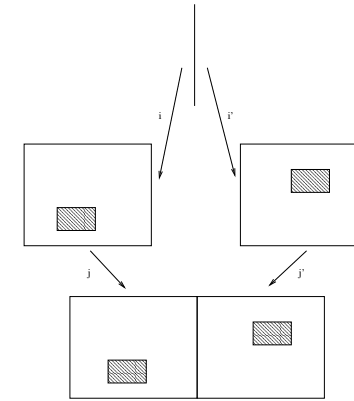
Directed homotopy is not "standard" homotopy

- 18 -

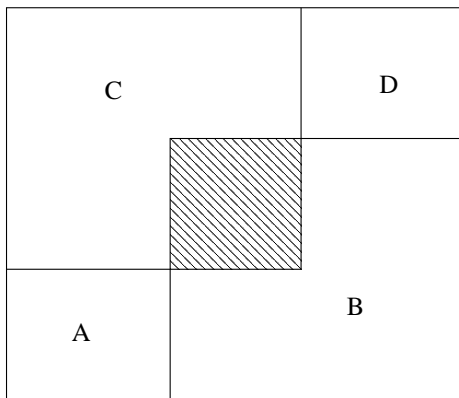
$\vec{\pi}_1$  of a product [parallel “independent” composition]



A Seifert/van Kampen theorem [compositionality]



Example of a  $\vec{\pi}_1$



Homotopy classes

	A	B	C	D
A	1	1	1	2
B	0	1	0	1
C	0	0	1	1
D	0	0	0	1

→ compression or (finite) presentation of the fundamental category?

## Future components

Let  $\mathcal{C}$  be a directed category.  $\Sigma$  is a subcategory of future weak equivalences ( $f$ -WE) if:

- $\Sigma$  contains all isos of  $\mathcal{C}$ .
- all  $\sigma$  in  $\Sigma$  are epis in  $\mathcal{C}$ .
- $\Sigma$  is stable under pushout (which always exists, with any morphism in  $\mathcal{C}$ ).
- If there is  $u : \beta \rightarrow \gamma$  in  $\mathcal{C}$ , then for all  $\sigma : \alpha \rightarrow \beta$  in  $\Sigma$ , and all  $f : \alpha \rightarrow \gamma$  in  $\mathcal{C}$ ,  $f$  factors through  $\sigma$ , that is, there exists  $h : \beta \rightarrow \gamma$  such that the following diagram commutes



- 27 -

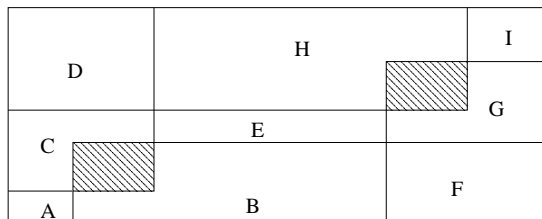
## Duals and existence

- (other definitions possible - such as weaker version by Lisbeth)
- Dual notion  $p$ -WE, bi-notion  $WE$ .
- In directed categories, there always exists  $f$ -WE,  $p$ -WE and  $WE$  subcategories, namely the subcategory of isomorphisms of  $\mathcal{C}$ .

- 28 -

## A finite "invariant"?

"disconnected components" (category of fractions of the fundamental category):



(with L. Fajstrup, E. Haucourt and M. Raussen)

- 25 -

## Directed categories

- Let  $\mathcal{C}$  be a category,  $\Sigma$  a subcategory of  $\mathcal{C}$ .  $\Sigma$  is pure in  $\mathcal{C}$  if for all  $f, g$  in  $\mathcal{C}$ ,  $f \circ g \in \Sigma$  implies  $f \in \Sigma$  and  $g \in \Sigma$ .
- A directed category is a category whose subcategory of isomorphisms is pure.
- For  $X$  a po-space, local po-space etc.  $\vec{\pi}_1(X)$  is a directed category.

- 26 -

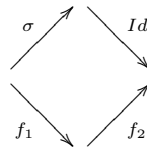
## Purity

---

Let  $\Sigma$  be a subcategory of WE (respectively,  $f$ -WE,  $p$ -WE) in  $\mathcal{C}$ , then  $\Sigma$  is (respectively left, right) pure.

Sketch of proof.

Suppose  $\sigma$  in  $\Sigma$  is equal to  $f_2 \circ f_1$  with  $f_1$  and  $f_2$  in  $\mathcal{C}$ :

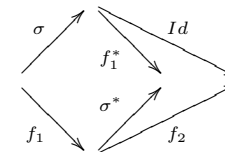


- 31 -

## Sketch of proof

---

As  $\sigma$  is in  $\Sigma$ , we have a pushout between  $\sigma$  and  $f_1$ , hence we have the commutative diagram



- 32 -

## WE and left/right calculi

---

- $p$ -WE form right calculi, and
- $f$ -WE form left calculi,
- WE form left and right calculi.

- 29 -

## Left and right purity

---

- $\Sigma$  is left pure if for all  $\sigma$  in  $\Sigma$ , and for all  $f_1$  and  $f_2$  in  $\mathcal{C}$  such that  $\sigma = f_2 \circ f_1$ , then  $f_1$  is in  $\Sigma$ .
- $\Sigma$  is right pure if (...), then  $f_2$  is in  $\Sigma$ .
- $\Sigma$  is pure if it is both left and right pure.

- 30 -

## Maximal WE subcategories

---

Let  $\mathcal{C}$  be a directed category. There exists a maximal subcategory of WE ( $f$ -WE,  $p$ -WE respectively) in  $\mathcal{C}$ .

Sketch of proof.

There exists one, as we saw earlier.

Now, it suffices to show that if  $\tau$  is a morphism of  $\mathcal{C}$  satisfying all axioms of a subcategory of WE (as the category generated by  $\tau$ ) and if  $\Sigma$  is a subcategory of WE, then all composites  $\tau \circ \sigma$  and  $\sigma \circ \tau$ , together with  $\Sigma$ , is a subcategory of WE. By induction, we see that being WE is inductive. Using Zorn's lemma, we find the maximal WE.

- 35 -

## Consequence...

---

Using this maximal WE, we have all the results from APCS'04, and in particular:

Let  $\mathcal{C}$  be a category in which all endomorphisms are identities. Then there is a maximal WE subcategory  $\Sigma$  in  $\mathcal{C}$ . Furthermore, let  $C_1, C_2 \subset Ob(\mathcal{C})$  denote two components such that the set of morphisms (in  $\mathcal{C}/\Sigma$ ) is *finite*. Then, for every  $x_1 \in C_1$  there exists  $x_2 \in C_2$  such that the quotient map

$$\mathcal{C}(x_1, x_2) \rightarrow \mathcal{C}/\Sigma(C_1, C_2), ; f \mapsto [f]$$

is *bijective*.

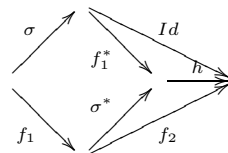
Similarly with just  $f$ -WE (we can choose the target point only) and the  $p$ -WE (we can choose the source point only).

- 36 -

## Sketch of proof

---

hence, by the universality of the pushout, we have a unique  $h$  in  $\mathcal{C}$  such that the diagram below commutes



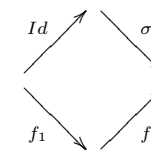
This implies that  $Id = h \circ f_1^*$ . Hence  $h$  is a left inverse in  $\mathcal{C}$  hence is in  $\Sigma$ . This also implies that  $f_2 = h \circ \sigma^*$ , a composite of two elements of  $\Sigma$ , hence is in  $\Sigma$ .

- 33 -

## Sketch of proof

---

Now we can rewrite  $\sigma = f_2 \circ f_1$  as the commutative diagram



and use the co-universal property of the pullback of  $\sigma$  along  $f_2$ , to conclude in the same manner that  $f_1$  is in  $\Sigma$ .

- 34 -

## Theorem

---

Let  $\Sigma$  be the inessential morphisms in the future, in the category  $\mathcal{C} = \vec{\pi}_1(X)$  for some local po-space  $X$ .

Suppose that  $\Sigma$  is cocomplete (it is automatically the case in mutual exclusion models, i.e.  $\vec{T}^n$  minus isothetic hyperrectangles), then  $\mathcal{C}_\Sigma$  is reflective in  $\vec{\pi}_1(X)$ .

- 39 -

## Computations?

---

- We have a Seifert/van Kampen for local po-spaces (last ATMCS - or M. Grandis' proof)
- We also have a form of Seifert/van Kampen for components categories, "up to subdivision" (Emmanuel Haucourt), which is of value for practical computations.
- Also, some specific algorithms for mutual exclusion models (M. Raussen in dimension 2, and sub-optimal algorithm by E. Goubault in all dimensions).

- 40 -

## Orthogonal subcategories

---

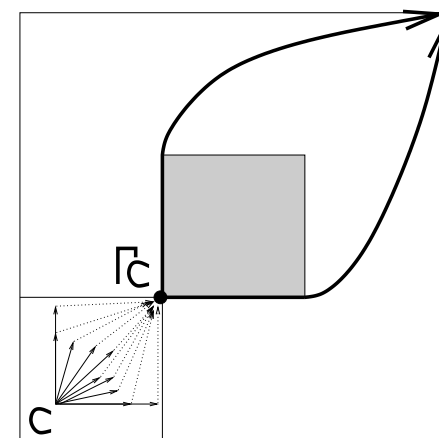
Let  $\mathcal{C}$  be a category and  $\Sigma$  a class of morphisms of  $\mathcal{C}$ . By the orthogonal subcategory of  $\mathcal{C}$  determined by  $\Sigma$ , we mean the full subcategory  $\mathcal{C}_\Sigma$  of  $\mathcal{C}$ , whose objects are those  $X \in \mathcal{C}$  such that  $s \perp X$  for every  $s \in \Sigma$ , i.e., such that for every  $s : A \rightarrow B \in \Sigma$ , for every morphism  $f : A \rightarrow X$ , there exists a unique morphism  $b : B \rightarrow X$  such that  $b \circ s = f$ .

$$\begin{array}{ccc}
 A & \xrightarrow{s \in \Sigma} & B \\
 \forall f \in \mathcal{C} \downarrow & & \searrow \exists! b \\
 X & & 
 \end{array}$$

- 37 -

## The orthogonal subcategory of $\Sigma_+$ is reflective

---



- 38 -

## A proposal for strong dihomotopy equivalence

For  $X$  a local po-space, we note  $\vec{\pi}_1(X)$  its fundamental category, and  $\Sigma_Y$  the maximal subcategory of inessential morphisms of  $\vec{\pi}_1(X)$ .

Let  $f : X \rightarrow Y$ . We say that  $f$  is a strong invariant if  $\vec{\pi}_1(f)$  maps the subcategory  $\Sigma_X$  of  $\vec{\pi}_1(X)$  into the subcategory  $\Sigma_Y$  of  $\vec{\pi}_1(Y)$ .

Let  $X$  and  $Y$  be two local po-spaces. We say that  $X$  and  $Y$  are dihomotopy equivalent if and if there exist strong invariant dimaps

$$X \begin{array}{c} \xrightarrow{f} \\ \xleftarrow{g} \end{array} Y$$

such that  $f \circ g \sim Id_Y$  and  $g \circ f \sim Id_X$ .

- 43 -

## Examples

---

- The directed interval is dihomotopy equivalent to a point, but...
- The wedge of two directed intervals (glued together at their start point) is not dihomotopy equivalent to a point nor a directed interval...

- 44 -

## If we want to go further

---

- $\vec{\pi}_0$ !
- (Strong) dihomotopy equivalence
- Higher-dimensional fundamental categories (difficult)
- Model-category theoretic explanation of dihomotopy (P. Gaucher, or K. Hess/K. Worytkiewicz/P. Bubenik)

- 41 -

## A proposal for $\vec{\pi}_0$

---

Let  $U : Cat \rightarrow Poset$  be the forgetful functor from the category of small categories to the category of posetal categories (the ones with at most one arrow between two objects). Let  $X$  be a local po-space. Let  $\vec{\pi}_0(X)$ , the set of diconnected components, be defined as the set of arrows of  $U(\vec{\pi}_1(X))$ .

The set of diconnected components is to be thought of as the set of possible bibase points that we need to "rigidify" the deformations of dimaps.

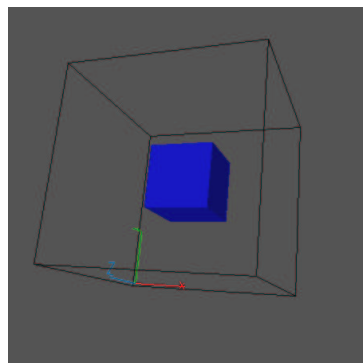
- 42 -

## Higher-dimensional dihomotopies

---

(in homology: in my thesis [1995]; also, in homotopy, see S. Sokolowski - more recently, M. Grandis)

**Observation** of  $k > 1$  degrees of freedom



→ higher-dimensional loops ( $\pi_k$ ): around dipaths  $\zeta$ .

## Possible $\pi_n$ ( $n \geq 2$ )

---

$$\pi_n(X)(x_0, x_1) = \vec{\pi}_1((X, \leq)^{(S^{n-1}, =)}(x_0, x_1))$$

(where  $x_0$  et  $x_1$  are identified with  $(n - 1) - loops$ )

Therefore:

$$- \vec{\pi}_2(\vec{I}^3)(i, f) = \{*\}$$

-  $\vec{\pi}_1(\vec{I}^3 \setminus \{(1/2, 1/2, 1/2)\})(i, f) = \{*\}$  but its  $\vec{\pi}_2$  is  $\mathbb{Z}$  (with "lateral composition") and its  $\vec{\pi}_3$  is not  $\{*\}$  but  $\mathbb{Z}$  (because of an analogous of the Hopf function)

- all the homotopies of spheres are lifted  $\zeta$  in  $\vec{\pi}_n(\vec{I}^k \setminus \{*\})$

Algebraic model of dihomotopy  $n$ -types?