

Interpretable treatment regimes via decision lists

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Outline: talk in two parts

- ▶ Interpretable treatment regimes
- ▶ Open problems

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- ▶ **Interpretable treatment regimes**
- ▶ Open problems

Precision medicine

- ▶ “The right treatment for the right patient at the right time.”
 - Mantra of precision medicine advocates
 - ▶ Widely recognized that best clinical care requires treatment decisions tailored to individual patient characteristics
 - ▶ Improve patient outcomes, reduce cost and patient burden
- ▶ Treatment regimes
 - ▶ Formalize clinical decision making as sequence of decision rules
 - ▶ One rule per stage of clinical intervention
 - ▶ Maps current patient info to recommended treatment
 - ▶ Optimal regime maximizes the mean of some cumulative clinical outcome if applied to population of interest

Ex. Treatment regime: mHealth for PTSD in cancer patients (PI S. Smith)

First stage decision rule

If distress ≥ 3 **then:** Cancer Distress Coach (CDC)

Else if PTSD symptom score ≥ 20 **then:** CDC

Else: usual care

Second stage decision rule

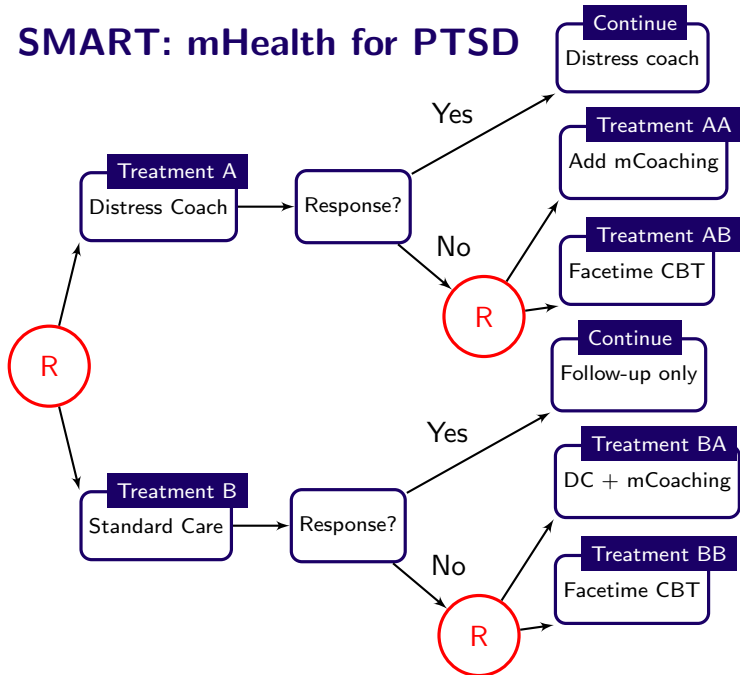
If responder **then:** continue first stage treatment

Else if using CDC and PTSD change ≥ 3 **then:** add mCoaching

Else if using CDC and distress ≥ 4 **then:** add FaceTime CBT

Else FaceTime CBT only

Ex. SMART: mHealth for PTSD

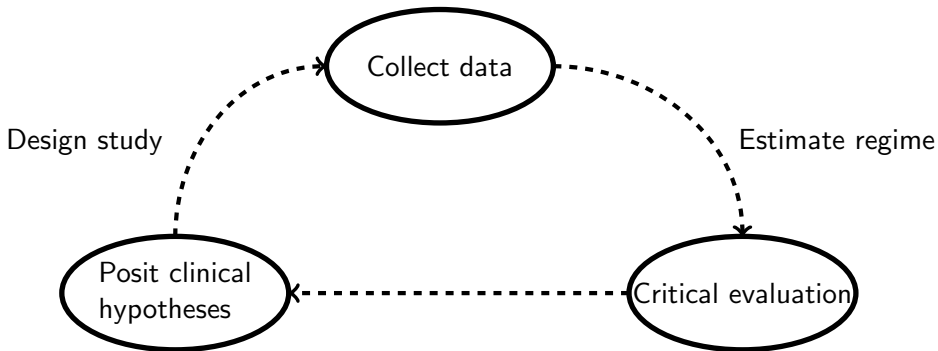


Estimation of treatment regimes: recent trend

- ▶ Current paradigm: assume estimated regime used to dictate treatment choice \Rightarrow emphasize flexibility over interpretability
- ▶ Surge in machine-learning/semi-parametric methods
 - ▶ Direct-search with large-margin classifiers (Zhao et al. 2012, 2013ab, 2014; Kang et al., 2014; Zhao and L., 2015)
 - ▶ Generalized additive models (Moodie et al. 2014)
 - ▶ Nearest-neighbor methods (Zhou and Kosorok, 2016)
 - ▶ JSM JASA T&M (2016) and A&CS (2016, 2017) discussed papers about non-parametric estimation of treatment regimes (Xu et al. 2016; Chen et al., 2016, Rashid et al., 2017)

Treatment regimes and clinical research

- ▶ Reality: estimated regimes part of secondary, exploratory analyses \Rightarrow emphasize interpretability in domain context
- ▶ Treatment regimes for application in clinical practice requires longterm, joint-effort of statisticians and clinical scientists



List-based regimes

- ▶ Goal: estimation of an interpretable yet expressive regime
 - ▶ List-based rules are a sequence of if-then statements mapping logical clauses to treatment recommendations
 - ▶ Regime comprising list-based decision rules are immediately interpretable in a domain context

If c_1 **then:** a_1
Else if c_2 **then:** a_2
...
Else if c_{L-1} **then:** a_{L-1}
Else: a_L

If $\text{distress} \geq 3$ **then:** CDC
Else if $\text{PTSD} \geq 20$ **then:** CDC
Else: usual care

List-based regimes cont'd

- ▶ Simple but powerful
 - ▶ Txt a if and only if all $\{c_1, \dots, c_k\}$ hold
 - ▶ Txt a if any of $\{c_1, \dots, c_k\}$ hold
 - ▶ Different treatment for each level of categorical variable
 - ▶ ...
- ▶ Restrict attention to clauses dictated by union or intersection of thresholded regions
 - ▶ $X_j > \tau_j$
 - ▶ $X_j \leq \tau_j$
 - ▶ $X_j > \tau_j$ and $X_k > \tau_k$
 - ▶ $X_j > \tau_j$ and $X_k \leq \tau_k$
 - ▶ $X_j > \tau_j$ or $X_k > \tau_k$
 - ▶ $X_j \geq \tau_j$ or $X_k \leq \tau_k$
 - ▶ $X_j \leq \tau_j$ and $X_k \leq \tau_k$
 - ▶ $X_j \leq \tau_j$ and $X_k > \tau_k$
 - ▶ $X_j \leq \tau_j$ or $X_k \leq \tau_k$
 - ▶ $X_j \leq \tau_j$ or $X_k > \tau_k$

List-based regimes and short-circuiting

- ▶ List-based regimes need not be unique

π
If c_1 then: a_1
Else if c_2 then: a_2
Else: a_3

π'
If $\neg c_1$ and $\neg c_2$ then: a_3
Else if $\neg c_1$ then: a_2
Else: a_1

- ▶ Choose regime that requires least patient burden/cost among equivalence class dictated by marginal mean outcome
 - ▶ Ex. π need not evaluate c_2 among patients satisfying c_1
 - ▶ Focus on estimating a single member of equivalence class

Setup and notation

- ▶ Observe $\{(\mathbf{X}_{1,i}, A_{1,i}, \dots, \mathbf{X}_{T,i}, A_{T,i}, Y_i)\}_{i=1}^n$ *i.i.d.* from P
 - ▶ $\mathbf{X}_t \in \mathbb{R}^{p_t}$ subject info during stage t
 - ▶ $A_t \in \mathcal{A}_t$ assigned txt at stage t
 - ▶ $Y \in \mathbb{R}$ outcome coded so that higher is better
- ▶ Define history $\mathbf{H}_1 = \mathbf{X}_1$, $\mathbf{H}_t = (\mathbf{H}_{t-1}^\top, A_{t-1}, \mathbf{X}_t^\top)^\top$, $t \geq 2$
- ▶ Treatment regime $\boldsymbol{\pi} = (\pi_1, \dots, \pi_T)$ where

$$\pi_t : \text{supp } \mathbf{H}_t \rightarrow \text{supp } \mathcal{A}_t,$$

patient presenting with $\mathbf{H}_t = \mathbf{h}_t$ assigned txt $\pi_t(\mathbf{h}_t)$

Optimal regime via potential outcomes

- ▶ Define $\bar{a}_t = (a_1, \dots, a_t)$ and set of potential outcomes

$$W^* = \left\{ \mathbf{H}_1, \mathbf{H}_2^*(a_1), \dots, \mathbf{H}_T^*(\bar{a}_{T-1}), Y^*(\bar{a}_T) : \bar{a}_T \in \otimes_{t=1}^T \mathcal{A}_t \right\}$$

- ▶ Potential outcome under a regime π

$$Y^*(\pi) = \sum_{\bar{a}_T} Y^*(\bar{a}_T) \prod_{t=1}^T 1[\pi_t \{ \mathbf{H}_t^*(\bar{a}_{t-1}) \} = a_t]$$

- ▶ Optimal regime in class Π satisfies $\mathbb{E} Y^*(\pi^{\text{opt}}) \geq \mathbb{E} Y^*(\pi)$, where $\pi^{\text{opt}}, \pi \in \Pi$

Characterizing the optimal regime

- ▶ For each $t = 1, \dots, T$ assume
 - (C1) Sequential ignorability: $A_t \perp W^* | \mathbf{H}_t$
 - (C2) Positivity: $P(A_t = a_t | \mathbf{H}_t) \geq \epsilon$ wp1 for some $\epsilon > 0$
 - (C3) Consistency: $\mathbf{H}_t = \mathbf{H}_t^*(\bar{A}_t)$, $Y = Y^*(\bar{A}_T)$
 - (C4) Stable unit treatment value assumption (SUTVA)
- ▶ (C1)-(C3) are satisfied by construction in a sequential multiple assignment randomized trial (SMART; Murphy, 2005)

Characterizing the optimal regime cont'd

- ▶ Let Π_t denote space of list-based rules on $\text{supp } \mathbf{H}_t$ for $t \geq 1$
- ▶ Assume (C1)-(C4) then
 - ▶ Define

$$Q_T(\mathbf{h}_T, a_T) = \mathbb{E} (Y | \mathbf{H}_T = \mathbf{h}_T, A_T = a_T)$$

$$\text{then } \pi_T^{\text{opt}} = \arg \max_{\pi_T \in \Pi_T} \mathbb{E} Q_T \{ \mathbf{H}_T, \pi_T(\mathbf{H}_T) \}$$

- ▶ Recursively, define

$$Q_t(\mathbf{h}_t, a_t) = \mathbb{E} [Q_{t+1} \{ \mathbf{H}_{t+1}, \pi_{t+1}^{\text{opt}}(\mathbf{H}_{t+1}) \} | \mathbf{H}_t = \mathbf{h}_t, A_t = a_t]$$

$$\text{then } \pi_t^{\text{opt}} = \arg \max_{\pi_t \in \Pi_t} \mathbb{E} Q_t \{ \mathbf{H}_t, \pi_t(\mathbf{H}_t) \}$$

Q-learning with policy search

- ▶ Let \mathcal{Q}_t denote postulated class of models for $Q_t(\mathbf{h}_t, a_t)$
- ▶ Estimation algorithm
 - ▶ Compute

$$\hat{Q}_T = \arg \min_{Q_T \in \mathcal{Q}_T} \left[\mathbb{P}_n \{ Y_T - Q_T(\mathbf{H}_T, A_T) \}^2 + \mathcal{P}_T(Q_T) \right]$$

and subsequently $\hat{\pi}_T = \arg \max_{\pi_T \in \Pi_T} \mathbb{P}_n \hat{Q}_T \{ \mathbf{H}_T, \pi_T(\mathbf{H}_T) \}$

- ▶ Recursively, compute

$$\hat{Q}_t = \arg \min_{Q_t \in \mathcal{Q}_t} \left\{ \mathbb{P}_n \left[\hat{Q}_{t+1} \{ \mathbf{H}_{t+1}, \hat{\pi}_{t+1}(\mathbf{H}_{t+1}) \} - Q_t(\mathbf{H}_t, A_t) \right]^2 + \mathcal{P}_t(Q_t) \right\}$$

and subsequently $\hat{\pi}_t = \arg \max_{\pi \in \Pi_t} \mathbb{P}_n \hat{Q}_t \{ \mathbf{H}_t, \pi_t(\mathbf{H}_t) \}$

Computation

- ▶ Π_t class of list-based rules \Rightarrow computation of $\arg \max_{\pi_t \in \Pi_t} \mathbb{P}_n \widehat{Q}_t \{ \mathbf{H}_t, \pi_t(\mathbf{H}_t) \}$ discrete opt. problem
- ▶ Basic idea: stepwise splitting procedure in spirit of CART
 - ▶ Optimize marginal mean outcome plus complexity penalty
 - ▶ Stopping criteria based on significance test

Lemma

Let $m_t = \#\mathcal{A}_t$, $d_t = \dim(\mathbf{h}_t)$, and L_t is the maximum list depth. Then, the time complexity for computing $\widehat{\boldsymbol{\pi}} = (\widehat{\pi}_1, \dots, \widehat{\pi}_T)$ is

$$O \left\{ n \log(n) \sum_{t=1}^T L_t m_t d_t^2 \right\}.$$

Convergence of Q-learning with policy search

- ▶ Overview of technical assumptions

- (A1) \mathbf{H}_t and Y are bounded with probability one

- (A2) Q-functions are sufficiently smooth (weakly differentiable in sense of Eberts and Steinwart, 2013, Defn. 2.1 with L_P norm)

- (A3) Margin condition on the treatment effects

- (A4) Estimation via kernel ridge regression with Gaussian kernel

- (A5) Rate conditions on complexity penalty in splitting criteria

Convergence of Q-learning with policy search cont'd

Lemma

Assume (C1)-(C4) and (A1)-(A5). Then, for each $t = 1, \dots, T$
 $P \left\{ \hat{\pi}_t(\mathbf{H}_t) \neq \pi_t^{\text{opt}}(\mathbf{H}_t) \mid \mathbb{P}_n \right\}$ converges to zero in probability.

Corollary

Assume (C1)-(C4) and (A1)-(A5). Then $\mathbb{E}Y^*(\boldsymbol{\pi}^{\text{opt}}) - \mathbb{E}Y^*(\hat{\boldsymbol{\pi}})$
converges to zero.

Q-learning with policy search discussion

- ▶ Divorce form of Q -function from class of regimes
- ▶ Decision lists offer interpretable yet expressive class of regimes
 - ▶ Diagnostics via comparison of $\arg \max_{a_t} \hat{Q}_t(\mathbf{h}_t, a_t)$ with $\hat{\pi}_t(\mathbf{h}_t)$
 - ▶ Short-circuiting can save cost/burden
- ▶ Potential drawbacks and open problems
 - ▶ Sub-parametric rates of convergence (not shown)
 - ▶ Methods for inference and uncertainty quantification needed

Simulation experiments: overview

- ▶ Settings taken from Zhao et al. (2015) and Murphy (2003)
- ▶ Basic framework
 - ▶ Normal covariates with AR-1 updates
 - ▶ Txt assign. mimics both randomized and observational study
 - ▶ Mean outcome nonlinear in history

Model	Stages	Covariates	Propensity	Source
1	2	50	Constant	Zhao et al.
2	2	50	History-dependent	Zhao et al.
3	3	3	Constant	Zhao et al.
4	10	10	History-dependent	Murphy

Simulation experiments: overview cont'd

- ▶ Performance measure $\mathbb{E} \{ \mathbb{E} Y^*(\hat{\pi}) \}$
 - ▶ Q-learning + Policy search with decision lists
 - ▶ Non-parametric Q-learning with random forests
 - ▶ Linear Q-learning with lasso penalty
 - ▶ Backward outcome weighted learning (BOWL)
- ▶ Additional numerical details
 - ▶ Use 1K Monte Carlo replications
 - ▶ Performance estimated with test set of size 10K
 - ▶ Consider training sets of size $n = 100$ and $n = 400$
 - ▶ Maximum list-depth set to $L_t = 5$ for all t

Simulation experiments: results

Model	n	Decision List	Q-RF	Q-Lasso	BOWL
1	100	6.63	6.70	6.50	6.70
1	400	6.94	6.70	6.66	6.70
2	100	3.66	3.41	3.68	2.68
2	400	3.73	3.71	3.75	3.19
3	100	14.49	12.94	5.74	8.12
3	400	18.60	18.02	8.42	13.62
4	100	23.68	17.83	12.39	NA
4	400	26.80	24.73	16.58	NA

Simulation experiments: summary

- ▶ Q-learning + policy search with decision lists performs favorably to parametric and non-parametric competitors
 - ▶ Parsimony of list provides automatic variable selection
 - ▶ Did not consider dense but weak signals
 - ▶ Significantly more interpretable than alternatives
 - ▶ R package **decisionList** freely available on CRAN

Discussion of list-based optimal regimes

- ▶ Estimation of optimal treatment regimes often part of secondary, hypothesis-generating analyses
- ▶ Q-learning + policy search with decision lists is a powerful tool for estimating high-quality interpretable regimes
 - ▶ Computationally efficient
 - ▶ Consistent under weak conditions
 - ▶ Because of underlying regression framework extends to high-dimensional data, censored data, continuous txts etc.
 - ▶ Applies to infinite horizon problems modeled as Markov Decision Processes through Bellman optimality est. equations

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Research-practice gap

- ▶ Active methods work
 - ▶ Machine learning
 - ▶ Infinite horizon problems
 - ▶ Clustered designs and regimes
- ▶ Most active methods work under framework considered here
 - ▶ Single outcome
 - ▶ Single decision maker
 - ▶ Stationary preferences
 - ▶ ...

Research-practice gap cont'd

- ▶ Need decision-support systems that faithfully reflect the complexities and realities of clinical decision making
 - ▶ Heterogeneous patient preferences
 - ▶ Multiple stakeholders with different objectives
 - ▶ Implementation costs
 - ▶ Non-stationarity
- ▶ Need to expand current mathematical framework

Individual patient preference

- ▶ Clinical decision-making requires balancing multiple, possibly competing outcomes
 - ▶ Ex., side-effects and efficacy
 - ▶ Ex., cost and local availability
 - ▶ ...
- ▶ Preferences across outcomes can vary across patients and within patients over time
 - ▶ Ex., become averse to side-effect after experiencing it
 - ▶ Ex., lethargy and lifestyle
 - ▶ Ex., hypertension and weight gain

Composite outcomes

- ▶ Idea: create a single composite summary across all outcomes
 - ▶ Assumes homogeneous preference across all patients
 - ▶ Thall et al. have applied this approach successfully in cancer
- ▶ Potential problems
 - ▶ Preferences vary across patients
 - ▶ Preferences change over time

Preference elicitation

- ▶ Idea! ask patients about their preferences
 - ▶ Administer questionnaire, link answers to utility function through latent preference model, e.g., item response model
 - ▶ Questionnaire becomes part of treatment package
 - ▶ Leads to regime based on individual patient preference
- ▶ Potential problems
 - ▶ Need high-quality instruments
 - ▶ Patients unable/unwilling to communicate preferences

Set-valued regimes

- ▶ Idea! screen-out treatment choices that are dominated across all outcomes under consideration
 - ▶ Recommend set of treatment options
 - ▶ Includes optimal regime for large class of preferences
 - ▶ Avoid elicitation or composite outcomes
- ▶ Potential problems
 - ▶ Little guidance on how to choose among set
 - ▶ Individual preference only incorporated indirectly

Informing, not dictating

- ▶ Supplement domain expertise with data
 - ▶ Distill data into information
 - ▶ Communicate strength of evidence provided by data
- ▶ Health communication is notoriously difficult
 - ▶ Health literacy varies widely
 - ▶ Shared decision model can be time and resource intensive

Informing, not dictating cont'd

- ▶ Methodology must be informed by clinical need
 - ▶ Not all statistical/methodological challenges
 - ▶ Information communication tools needed
- ▶ Many important open problems
 - ▶ Extensions to more exotic data types/gen models
 - ▶ Research-translation

Thank you.

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