## Finite Element Exterior Calculus and Applications

Part II

Douglas N. Arnold, University of Minnesota Peking University/BICMR August 15–18, 2015 The fundamental theorem of numerical analysis

The basic idea:

Continuous problem:  $L : X \to Y$  bounded linear operator between Banach spaces

Given  $f \in Y$  find  $u \in X$  such that Lu = f.

**Discrete problem**:  $L_h : X_h \to Y_h$  operator on finite dimensional spaces.

Given  $f_h \in Y_h$  find  $u_h \in X_h$  such that  $L_h u_h = f_h$ 

- The discretization is *convergent* if *u<sub>h</sub>* is sufficiently near *u*.
- The discretization is *consistent* if  $L_h$  and  $f_h$  are sufficiently near L and f.
- The discretization is *stable* if the discrete problem is well-posed.

#### THEOREM (FUNDAMENTAL THEOREM OF NUMERICAL ANALYSIS)

A discretization which is consistent and stable is convergent.

To quantify convergence we use

- 1. A norm in the space  $X_h$ .
- 2. A representative  $U_h$  in  $X_h$ .

The *discretization error* is then  $||U_h - u_h||_{X_h}$ . The method is convergent if it tends to 0 as  $h \to 0$ .

To quantify convergence we use

- 1. A norm in the space  $X_h$ .
- 2. A representative  $U_h$  in  $X_h$ .

The *discretization error* is then  $||U_h - u_h||_{X_h}$ . The method is convergent if it tends to 0 as  $h \to 0$ .

To quantify consistency we use a norm in the space  $Y_h$ . The *consistency error* is then  $||L_h U_h - f_h||_{Y_h}$ . The method is consistent if it tends to 0.

To quantify convergence we use

- 1. A norm in the space  $X_h$ .
- 2. A representative  $U_h$  in  $X_h$ .

The *discretization error* is then  $||U_h - u_h||_{X_h}$ . The method is convergent if it tends to 0 as  $h \to 0$ .

To quantify consistency we use a norm in the space  $Y_h$ . The *consistency error* is then  $||L_h U_h - f_h||_{Y_h}$ . The method is consistent if it tends to 0.

The *stability constant* is  $\|L_h^{-1}\|_{\mathcal{L}(Y_h, X_h)}$ . The method is stable if it remains bounded as  $h \to 0$ .

To quantify convergence we use

- 1. A norm in the space  $X_h$ .
- 2. A representative  $U_h$  in  $X_h$ .

The *discretization error* is then  $||U_h - u_h||_{X_h}$ . The method is convergent if it tends to 0 as  $h \to 0$ .

To quantify consistency we use a norm in the space  $Y_h$ . The *consistency error* is then  $||L_h U_h - f_h||_{Y_h}$ . The method is consistent if it tends to 0.

The *stability constant* is  $\|L_h^{-1}\|_{\mathcal{L}(Y_h, X_h)}$ . The method is stable if it remains bounded as  $h \to 0$ .

In this context the fundamental theorem is easy:

$$L_{h}u_{h} = f_{h} \Longrightarrow L_{h}U_{h} - L_{h}u_{h} = L_{h}U_{h} - f_{h} \Longrightarrow U_{h} - u_{h} = L_{h}^{-1}(L_{h}U_{h} - f_{h})$$
$$\|U_{h} - u_{h}\|_{X_{h}} \le \|L_{h}^{-1}\|_{\mathcal{L}(Y_{h},X_{h})}\|L_{h}U_{h} - f_{h}\|_{Y_{h}}$$

To quantify convergence we use

- 1. A norm in the space  $X_h$ .
- 2. A representative  $U_h$  in  $X_h$ .

The *discretization error* is then  $||U_h - u_h||_{X_h}$ . The method is convergent if it tends to 0 as  $h \to 0$ .

To quantify consistency we use a norm in the space  $Y_h$ . The *consistency error* is then  $||L_h U_h - f_h||_{Y_h}$ . The method is consistent if it tends to 0.

The stability constant is  $\|L_h^{-1}\|_{\mathcal{L}(Y_h, X_h)}$ . The method is stable if it remains bounded as  $h \to 0$ .

In this context the fundamental theorem is easy:

$$L_{h}u_{h} = f_{h} \Longrightarrow L_{h}U_{h} - L_{h}u_{h} = L_{h}U_{h} - f_{h} \Longrightarrow U_{h} - u_{h} = L_{h}^{-1}(L_{h}U_{h} - f_{h})$$
$$||U_{h} - u_{h}||_{X_{h}} \le ||L_{h}^{-1}||_{\mathcal{L}(Y_{h},X_{h})}||L_{h}U_{h} - f_{h}||_{Y_{h}}$$

# Discretization of Hilbert complexes

#### Motivation: why mixed formulation?

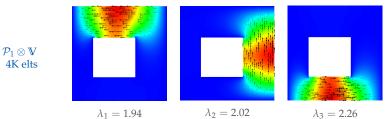
 $H^1 \xrightarrow{\text{grad}} H(\text{rot}) \xrightarrow{\text{rot}} L^2 \quad (dd^* + d^*d)u = (-\operatorname{grad}\operatorname{rot} + \operatorname{curl}\operatorname{rot})u = \lambda u$ 

Primal formulation: Find *u* such that  $(du, dv) + (d^*u, d^*v) = \lambda(u, v) \quad \forall v$ 

#### Motivation: why mixed formulation?

 $H^1 \xrightarrow{\text{grad}} H(\text{rot}) \xrightarrow{\text{rot}} L^2 \quad (dd^* + d^*d)u = (-\operatorname{grad}\operatorname{rot} + \operatorname{curl}\operatorname{rot})u = \lambda u$ 

Primal formulation: Find *u* such that  $(du, dv) + (d^*u, d^*v) = \lambda(u, v) \quad \forall v$ 

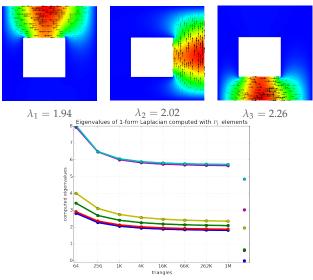


#### Motivation: why mixed formulation?

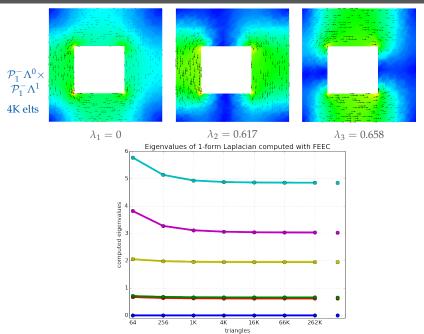
 $H^1 \xrightarrow{\text{grad}} H(\text{rot}) \xrightarrow{\text{rot}} L^2 \quad (dd^* + d^*d)u = (-\operatorname{grad} \operatorname{rot} + \operatorname{curl} \operatorname{rot})u = \lambda u$ 

Primal formulation: Find *u* such that  $(du, dv) + (d^*u, d^*v) = \lambda(u, v) \quad \forall v$ 

 $\begin{array}{c} \mathcal{P}_1\otimes\mathbb{V}\\ 4K \text{ elts} \end{array}$ 



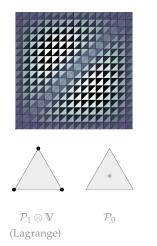
#### **Eigenvalues of the 1-form Hodge Laplacian (FEEC)**



## Motivation: why do we need special elements?

*Mixed Poisson eq:*  $H(\operatorname{div}) \xrightarrow{\operatorname{div}} L^2 \to 0$ .

The obvious choice of Lagrange  $\mathcal{P}_1$  for  $V^0$  and  $P_0$  for  $V^1$  is unstable. RT, BDM families are stable.







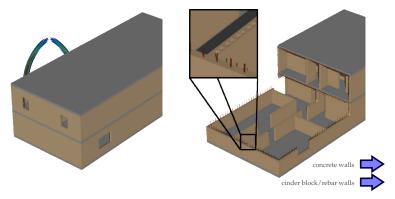
 $\mathcal{P}_1^- \Lambda^1$ (RT)



## Motivation: a real computation

Stowell-Fassenfass-White, IEEE Trans. Ant. & Prop. 2008

- Solved time-dependent Maxwell equations using  $Q_1^- \Lambda^1$  for *E* and  $Q_1^- \Lambda^2$  for *B* (Nédélec elements of the first kind on bricks)
- 10,114,695,855 brick elements ( $\approx$  1 cm resolution)
- $\approx 60,000,000,000$  unknowns
- $\approx$  12,000 time steps of 14 picoseconds



## Discretizing the mixed formulation

We therefore consider finite element discretizations of the mixed form:

Given 
$$f \in W^k$$
, find  $\sigma \in V^{k-1}$ ,  $u \in V^k$ , and  $p \in \mathfrak{H}^k$  s.t.

$$egin{aligned} &\langle \sigma, \tau 
angle - \langle u, d \tau 
angle &= 0, & au \in V^{k-1}, \ &\langle d \sigma, v 
angle + \langle d u, d v 
angle + \langle p, v 
angle &= \langle f, v 
angle, & v \in V^k, \ &\langle u, q 
angle &= 0, & q \in \mathfrak{H}^k. \end{aligned}$$

#### Discretizing the mixed formulation

We therefore consider finite element discretizations of the mixed form:

Given 
$$f \in W^k$$
, find  $\sigma \in V^{k-1}$ ,  $u \in V^k$ , and  $p \in \mathfrak{H}^k$  s.t.

$$egin{aligned} &\langle \sigma, \tau 
angle - \langle u, d \tau 
angle &= 0, & au \in V^{k-1}, \ &\langle d \sigma, v 
angle + \langle d u, d v 
angle + \langle p, v 
angle &= \langle f, v 
angle, & v \in V^k, \ &\langle u, q 
angle &= 0, & q \in \mathfrak{H}^k. \end{aligned}$$

• Choose f.d. subspaces  $V_h^j \subset V^j$ 

• Define  $\mathfrak{Z}_{h'}^{j}$ ,  $\mathfrak{B}_{h'}^{j}$ ,  $\mathfrak{H}_{h}^{j} = \{ v \in \mathfrak{Z}_{h}^{j} | v \perp \mathfrak{B}_{h}^{j} \}$ 

Given  $f \in W^k$ , find  $\sigma_h \in V_h^{k-1}$ ,  $u_h \in V_h^k$ , and  $p_h \in \mathfrak{H}_h^k$  s.t.

$$egin{aligned} &\langle \sigma_h, au 
angle - \langle u_h, d au 
angle = 0, & au \in V_h^{k-1}, \ &\langle d\sigma_h, v 
angle + \langle du_h, dv 
angle + \langle p_h, v 
angle = \langle f, v 
angle, & v \in V_h^k, \ &\langle u_h, q 
angle = 0, & q \in \mathfrak{H}_h^k. \end{aligned}$$

For *any* choice of the  $V_h^j$  there exists a unique solution.

However, the consistency and stability of the numerical method depends vitally on the choice of subspaces.

Remark:

Note that  $\mathfrak{Z}_h \subset \mathfrak{Z}$ ,  $\mathfrak{B}_h \subset \mathfrak{B}$ , but in general  $\mathfrak{H}_h \not\subseteq \mathfrak{H}$ . So the mixed method is slightly *nonconforming*, and this also contributes to the consistency error.

We need the spaces  $V_h^j \subset V^j$  (at least for j = k - 1, k, k + 1) to satisfy three properties:

1. Approximation property: Of course  $V_h^j$  must afford good approximation of elements of  $V^j$ . This can be formalized with respect to a family of subspaces parametrized by *h* by requiring

$$\lim_{h \to 0} \inf_{v \in V_h^j} \|w - v\|_V = 0, \quad w \in V^j$$

(or =  $O(h^r)$  for w in some dense subspace, or ...)

2. Subcomplex property:  $dV_h^{k-1} \subset V_h^k$  and  $dV_h^k \subset V_h^{k+1}$ , so

$$V_h^{k-1} \xrightarrow{d} V_h^k \xrightarrow{d} V_h^{k+1}$$

is a subcomplex.

## **Bounded cochain projection**

3. Bounded cochain projection: Most important, we assume that there exists a *cochain map* from the H-complex to the subcomplex which is a *projection* and is *bounded*.

$$V^{k-1} \xrightarrow{d} V^k \xrightarrow{d} V^{k+1}$$

$$\pi_h^{k-1} \downarrow \qquad \pi_h^k \downarrow \qquad \pi_h^{k+1} \downarrow$$

$$V_h^{k-1} \xrightarrow{d} V_h^k \xrightarrow{d} V_h^{k+1}$$

- For now, boundedness is in *V*-norm:  $\|\pi_h v\|_V \le c \|v\|_V$ . But later we will need *W*-boundedness, which is a stronger requirement.
- A bounded projection is *quasioptimal*:

$$\|v - \pi_h v\|_V \le c \inf_{w \in V_h^j} \|v - w\|_V, \quad v \in V^j$$

From the subcomplex property

$$V_h^{k-1} \xrightarrow{d} V_h^k \xrightarrow{d} V_h^{k+1}$$

is itself a closed H-complex. (We take  $W_h^k = V_h^k$  but with the W-norm.)

Therefore there is a discrete adjoint operator  $d_h^*$  (its domain is all of  $W_h^k$ ), a discrete Hodge decomposition

 $V_h^k = \mathfrak{B}_h^k \oplus \mathfrak{H}_h^k \oplus \mathfrak{B}_{kh}^k.$ 

and a discrete Poincaré inequality

$$\|z\|_V \leq c_h^P \|dz\|, \quad z\in \mathfrak{Z}_h^{k\perp_{V_h}}.$$

#### Theorem

Given: a closed H-complex, and a choice of f.d. subspaces satisfying the subcomplex property and admitting a V-bdd cochain projection  $\pi_h$ . Assume also the (very weak) approximation property

$$\|q-\pi_h q\|<\|q\|, \quad 0
eq q\in \mathfrak{H}^k.$$

Then  $\pi_h$  induces an isomorphism from  $\mathfrak{H}^k$  onto  $\mathfrak{H}^k_h$ . Moreover,

$$\operatorname{gap}(\mathfrak{H},\mathfrak{H}_h) \leq \sup_{\substack{q \in \mathfrak{H} \\ \|q\|=1}} \|q - \pi_h q\|_V.$$

$$\operatorname{gap}(\mathfrak{H},\mathfrak{H}_h) := \max\left(\sup_{\substack{u \in \mathfrak{H} \\ \|u\|=1}} \inf_{v \in \mathfrak{H}_h} \|u - v\|_V, \sup_{\substack{v \in \mathfrak{H}_h \\ \|v\|=1}} \inf_{u \in \mathfrak{H}} \|u - v\|_V\right).$$

#### Theorem

*Given: a closed H-complex, and a choice of f.d. subspaces satisfying the subcomplex property and admitting a V-bdd cochain projection*  $\pi_h$ *. Then* 

$$\|v\|_V \le c^P \|\pi_h\| \|dv\|_V, \quad v \in \mathfrak{Z}_h^{k\perp} \cap V_h^k.$$

#### COROLLARY (STABILITY AND QUASIOPTIMALITY OF THE MIXED METHOD)

The mixed method is stable (uniform inf-sup condition) and satisfies

$$\begin{split} \|\sigma - \sigma_h\|_V + \|u - u_h\|_V + \|p - p_h\| \\ &\leq C(\inf_{\tau \in V_h^{k-1}} \|\sigma - \tau\|_V + \inf_{v \in V_h^k} \|u - v\|_V + \inf_{q \in V_h^k} \|p - q\|_V \\ &+ \mu \inf_{v \in V_h^k} \|p_{\mathfrak{B}} u - v\|_V), \end{split}$$
where  $\mu = \mu_h = \sup_{r \in \mathfrak{H}^k, \|r\| = 1} \|(I - \pi_h)r\|.$ 

#### Improved error estimates

In addition to  $\mu = ||(I - \pi_h)P_{\mathfrak{H}}||$ , define  $\delta, \eta = o(1)$  by

$$\delta = \| (I - \pi_h) K \|_{\text{Lin}(W,W)}, \quad \eta = \| (I - \pi_h) d^{[*]} K \|_{\text{Lin}(W,W)}.$$
  
When  $V_h^k \supset \mathcal{P}_r, \quad \mu = O(h^{r+1}), \quad \eta = O(h), \quad \delta = \begin{cases} O(h^2), & r > 0, \\ O(h), & r = 0, \end{cases}$ 

#### Theorem

Given: an H-complex satisfying the compactness property, and a choice of *f.d.* subspaces satisfying the subcomplex property and admitting a W-bdd cochain projection  $\pi_h$ . Then

 $\begin{aligned} \|d(\sigma - \sigma_h)\| &\leq cE(d\sigma), \qquad \|\sigma - \sigma_h\| \leq c[E(\sigma) + \eta E(d\sigma)], \\ \|d(u - u_h)\| &\leq c\{E(du) + \eta [E(d\sigma) + E(p)]\}, \\ \|u - u_h\| &\leq c\{E(u) + \eta [E(du) + E(\sigma)] \\ &+ (\eta^2 + \delta)[E(d\sigma) + E(p)] + \mu E(P_{\mathfrak{B}}u)\}. \end{aligned}$ 

 $-\operatorname{grad}\operatorname{div} u + \operatorname{curl}\operatorname{rot} u = f \text{ in } \Omega \text{ (unit square)}, \quad u \cdot n = \operatorname{rot} u = 0 \text{ on } \partial \Omega \text{ (magnetic BC)}$ 

$$0 \to H^1 \xrightarrow{\text{grad}} H(\text{rot}) \xrightarrow{\text{rot}} L^2 \to 0$$
  
$$\sigma_h \in V_h^0 \subset H^1, \quad u_h \in V_h^1 \subset H(\text{rot})$$
  
$$\langle \sigma_h, \tau \rangle - \langle u_h, \text{grad} \tau \rangle = 0, \qquad \tau \in V_h^{k-1},$$
  
$$\langle \text{grad} \sigma_h, v \rangle + \langle \text{rot} u_h, \text{rot} v \rangle = \langle f, v \rangle, \quad v \in V_h^k.$$

 $V_h^0$  Lagrange  $V_h^1$  R-T  $V_h^2$  DG

All hypotheses are met...

| $\ \sigma - \sigma_h\ $ | rate | $\ \nabla(\sigma-\sigma_h)\ $ | rate | $  u-u_h  $ | rate | $\ \operatorname{rot}(u-u_h)\ $ | rate |
|-------------------------|------|-------------------------------|------|-------------|------|---------------------------------|------|
| 2.16e-04                | 3.03 | 2.63e-02                      | 1.98 | 2.14e-03    | 1.99 | 1.17e-02                        | 1.99 |
| 2.70e-05                | 3.00 | 6.60e-03                      | 1.99 | 5.37e-04    | 1.99 | 2.93e-03                        | 2.00 |
| 3.37e-06                | 3.00 | 1.65e-03                      | 2.00 | 1.34e-04    | 2.00 | 7.33e-04                        | 2.00 |
| 4.16e-07                | 3.02 | 4.14e-04                      | 2.00 | 3.36e-05    | 2.00 | 1.83e-04                        | 2.00 |
|                         | 3    |                               | 2    |             | 2    |                                 | 2    |





## Numerical solution of vector Laplacian, Dirichlet BC

For Dirichlet boundary conditions,  $\sigma = -\operatorname{div} u$  is sought in  $H^1$ , u is sought in  $\mathring{H}(\operatorname{rot})$  (the BC  $u \cdot t = 0$  is essential,  $u \cdot n = 0$  is natural).

There is no complex, so our theory does not apply.

| σ -  | $-\sigma_h \ $ | rate | $\ \nabla(\sigma-\sigma_h)\ $ | rate | $  u-u_h  $ | rate | $\ \operatorname{rot}(u-u_h)\ $ | rate |
|------|----------------|------|-------------------------------|------|-------------|------|---------------------------------|------|
| 1.90 | )e-02          | 1.62 | 2.53e+00                      | 0.63 | 1.22e-03    | 2.01 | 1.55e-02                        | 1.58 |
| 6.36 | 6e-03          | 1.58 | 1.68e+00                      | 0.60 | 3.05e-04 r  | 2.00 | 5.33e-03                        | 1.54 |
| 2.18 | 3e-03          | 1.54 | 1.14e+00                      | 0.56 | 7.63e-05    | 2.00 | 1.85e-03                        | 1.52 |
| 7.58 | 3e-04          | 1.52 | 7.89e-01                      | 0.53 | 1.91e-05    | 2.00 | 6.49e-04                        | 1.51 |
|      |                | 1.5  |                               | 0.5  |             | 2    |                                 | 1.5  |

DNA-Falk-Gopalakrishnan M3AS 2011

Find 
$$\lambda \in \mathbb{R}$$
,  $0 \neq u \in D(L)$  s.t.  $Lu = \lambda u$ ,  $u \perp \mathfrak{H}$ 

 $\lambda ||u||^2 = ||du||^2 + ||d^*u||^2 > 0$  so  $\lambda > 0$  and  $Ku = \lambda^{-1}u$ .

By the compactness property,  $K : W^k \to W^k$  is compact and self-adjoint, so  $0 < \lambda_1 \le \lambda_2 \le \cdots \to \infty$ . Denote by  $v_i$  corresponding orthonormal eigenvalues,  $E_i = \mathbb{R}v_i$ .

Mixed discretization:

Find 
$$\lambda_h \in \mathbb{R}$$
,  $0 \neq (\sigma_h, u_h, p_h) \in V_h^{k-1} \times V_h^k \times \mathfrak{H}_h^k$  s.t.

$$egin{aligned} &\langle \sigma_h, au 
angle - \langle u_h, d au 
angle = 0, & au \in V_h^{k-1}, \ &\langle d\sigma_h, v 
angle + \langle du_h, dv 
angle + \langle p_h, v 
angle = \lambda_h \langle u_h, v 
angle, & v \in V_{h'}^k, \ &\langle u_h, q 
angle = 0, & q \in \mathfrak{H}_h^k. \end{aligned}$$

 $0 < \lambda_{1h} \leq \lambda_{2h} \leq \ldots \leq \lambda_{N_h h}$ ,  $v_{ih}$  orthonormal,  $E_{ih} = \mathbb{R} v_{ih}$ 

Let  $\sum_{i=1}^{m(j)} E_i$  be the span of the eigenspaces of the first *j* distinct eigenvalues. The method converges if  $\forall j, \epsilon > 0, \exists h_0 > 0$  s.t.

$$\max_{1 \le i \le m(j)} |\lambda_i - \lambda_{ih}| \le \epsilon \quad \text{and} \quad \operatorname{gap}\left(\sum_{i=1}^{m(j)} E_i, \sum_{i=1}^{m(j)} E_{i,h}\right) \le \epsilon \quad \text{if } h \le h_0.$$

A sufficient (and necessary) condition for eigenvalue convergence is operator norm convergence of the discrete solution operator  $K_h P_h$  to K (Kato, Babuska–Osborn, Boffi–Brezzi–Gastaldi):  $W \rightarrow W_h$  orthog.

The mixed discretization of the eigenvalue problem converges if

 $\lim_{h\to 0} \|K_h P_h - K\|_{\mathcal{L}(W,W)} = 0.$ 

## **Eigenvalue convergence follows from improved estimates**

$$\|u - u_h\| \le c\{E(u) + \eta[E(du) + E(\sigma)] + (\eta^2 + \delta)[E(d\sigma) + E(p)] + \mu E(P_{\mathfrak{B}}u)\}$$

$$E(d\sigma) + E(p) + E(P_{\mathfrak{B}}u) \le \|d\sigma\| + \|p\| + \|u\| \le \|f\|$$

$$E(u) \le \delta\|f\|, \quad E(du) + E(\sigma) \le \eta\|f\|$$

Therefore

$$\|(K - K_h P_h)f\| \le \delta + \eta^2 + \mu \to 0$$

Rates of convergence also follow, included doubled convergence rates for eigenvalues...